

Master Of Science in Computational Mechanics

Finite Elements in Fluids

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Assignment 1

Convert the conservative form of momentum conservation to non-conservative form

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \rho(\mathbf{v} \cdot \nabla)\mathbf{v} - \nabla \cdot \sigma = \rho \mathbf{b} \rightarrow \frac{\partial(\rho \mathbf{v})}{\partial t} + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v} - \sigma) = \rho \mathbf{b} \quad (1)$$

The conservative form of the linear momentum equation is,

$$\begin{aligned} \frac{\partial \rho \mathbf{v}}{\partial t} + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v} - \sigma) &= \rho \mathbf{b} \\ \rho \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) - \nabla \cdot \sigma &= \rho \mathbf{b} \end{aligned}$$

where,

$$\nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) = \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} \begin{bmatrix} \rho u u & \rho u v & \rho u z \\ \rho v u & \rho v v & \rho v z \\ \rho w u & \rho w v & \rho w z \end{bmatrix}$$

the x-component of the above equation will give:

$$\begin{aligned} & \frac{\partial(\rho u u)}{\partial x} + \frac{\partial(\rho v u)}{\partial y} + \frac{\partial(\rho w u)}{\partial z} \\ &= \rho \frac{\partial(uu)}{\partial x} + uu \frac{\partial \rho}{\partial x} + \rho \frac{\partial(vu)}{\partial y} + vu \frac{\partial \rho}{\partial y} + \rho \frac{\partial(wu)}{\partial z} + wu \frac{\partial \rho}{\partial z} \\ &= \rho \left(\frac{\partial(uu)}{\partial x} + \frac{\partial(vu)}{\partial y} + \frac{\partial(wu)}{\partial z} \right) + u \left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) \\ &= \rho \left(u \frac{\partial u}{\partial x} + u \frac{\partial u}{\partial x} + u \frac{\partial v}{\partial y} + v \frac{\partial u}{\partial y} + u \frac{\partial w}{\partial z} + w \frac{\partial u}{\partial z} \right) + u \begin{bmatrix} u & v & w \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial \rho}{\partial x} & \frac{\partial \rho}{\partial y} & \frac{\partial \rho}{\partial z} \end{bmatrix} \\ &= \rho \left(u \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) + u(\mathbf{v} \cdot \nabla \rho) \\ &= \rho \left(u(\nabla \cdot \mathbf{v}) + \mathbf{v} \cdot \nabla u \right) + u(\mathbf{v} \cdot \nabla \rho) \end{aligned}$$

similarly we can find y and z-components of the expression. Thus, it satisfy the equation

$$\nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) = \rho \left(\mathbf{v}(\nabla \cdot \mathbf{v}) + \mathbf{v} \cdot \nabla \mathbf{v} \right) + \mathbf{v}(\mathbf{v} \cdot \nabla \rho)$$

expanding the right hand side of the equation

$$\begin{aligned} & \rho \left(\mathbf{v}(\nabla \cdot \mathbf{v}) + \mathbf{v} \cdot \nabla \mathbf{v} \right) + \mathbf{v} \left(\nabla \cdot (\rho \mathbf{v}) - \rho(\nabla \cdot \mathbf{v}) \right) \\ &= \rho \mathbf{v}(\nabla \cdot \mathbf{v}) + \rho \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \nabla \cdot (\rho \mathbf{v}) - \rho \mathbf{v}(\nabla \cdot \mathbf{v}) \\ &= \rho \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \nabla \cdot (\rho \mathbf{v}) \end{aligned}$$

Substituting in equation (1):

$$\begin{aligned} \rho \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \frac{\partial \rho}{\partial t} + \rho \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \nabla \cdot (\rho \mathbf{v}) - \nabla \cdot \sigma &= \rho \mathbf{b} \\ \rho \frac{\partial \mathbf{v}}{\partial t} + \rho(\mathbf{v} \cdot \nabla)\mathbf{v} + \mathbf{v} \left(\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) \right) - \nabla \cdot \sigma &= \rho \mathbf{b} \\ \rho \frac{\partial \mathbf{v}}{\partial t} + \rho(\mathbf{v} \cdot \nabla)\mathbf{v} - \nabla \cdot \sigma &= \rho \mathbf{b} \end{aligned}$$