# Navier-Stokes numerical example

## Problem formulation

Navier-Stokes problem:

$$\begin{cases} -\nu\nabla^{2}\mathbf{v} + (\mathbf{v}\cdot\nabla)\mathbf{v} + \nabla p = \mathbf{b} & \text{in } \Omega\\ \nabla\cdot\mathbf{v} = 0 & \text{in } \Omega\\ \mathbf{v} = \mathbf{v}_{D} & \text{on } \Gamma_{D}\\ \mathbf{n}\cdot\sigma = \mathbf{t} & \text{on } \Gamma_{N} \end{cases}$$

Weak form:

$$\begin{aligned} a(\mathbf{w}, \mathbf{v}) + c(\mathbf{w}, \mathbf{v}, \mathbf{v}) + b(\mathbf{w}, p) &= (\mathbf{w}, \mathbf{b}) + (\mathbf{w}, \mathbf{t})_{\Gamma_N} & \forall \mathbf{w} \in \mathcal{V} \\ b(\mathbf{v}, q) &= 0 & \forall q \in \mathcal{Q} \end{aligned}$$

$$\begin{aligned} a(\mathbf{w}, \mathbf{v}) &= \nu(\nabla \mathbf{w}, \nabla \mathbf{v}) \\ b(\mathbf{v}, q) &= -(q, \nabla \cdot \mathbf{v}) \\ c(\mathbf{w}, \mathbf{v}, \mathbf{v}) &= (\mathbf{w}, (\mathbf{v} \cdot \nabla) \mathbf{v} = \int_{\Omega} \mathbf{w} \cdot (\mathbf{v} \cdot \nabla) \mathbf{v} \, d\Omega \end{aligned}$$

Galerkin discretization:

$$\begin{pmatrix} \mathbf{K} + \mathbf{C}(\mathbf{v}) & \mathbf{G} \\ \mathbf{G}^T & \mathbf{0} \end{pmatrix} \begin{pmatrix} \mathbf{u} \\ \mathbf{p} \end{pmatrix} = \begin{pmatrix} \mathbf{f} \\ \mathbf{h} \end{pmatrix}$$

### Discretization of the convective term for the Piccard's method

The following code shows the discretization for the linearized form of the convection matrix on the element level.

```
function [C] = ConvectionMatrix(X,T,referenceElement,velo)
...
v_igaus = N_ig*u_e;
Ce = Ce + Ngp'*(v_igaus(1)*Nx+v_igaus(2)*Ny)*dvolu;
...
```

end

. . .

## Discretization of the Newton-Raphson scheme

The following code shows the discretization for the linearized form of the convection matrix on the element level.

**function** [C1,C2] = ConvectionMatrix(X,T,referenceElement,velo)

The following code shows the implementation of the Newton-Raphson algorithm in the file mainNavierStokes.m:

```
. . .
    [C1, C2] = ConvectionMatrixNR(X, T, referenceElement, velo);
    Cred1 = C1(dofUnk, dofUnk);
    Cred2 = C2(dofUnk, dofUnk);
    A = [Kred + Cred1 Gred';
             zeros(nunkP)];
     Gred
    Atot = A;
    btot = [fred - (C1(dofUnk, dofDir)) * valDir; zeros(nunkP, 1)];
    J = [Kred + Cred1 + Cred2]
                                  Gred ';
     Gred
             zeros(nunkP)];
    F = Atot * sol0 - btot;
    % Computation of velocity and pressure increment
    solInc = -J \setminus F;
    % Update the solution
    veloInc = \mathbf{zeros}(\mathbf{ndofV}, 1);
    veloInc(dofUnk) = solInc(1:nunkV);
    presInc = solInc(nunkV+1:end);
    velo = velo + reshape(veloInc, 2, [])';
    pres = pres + presInc;
. . .
```

#### Results and convergence study

To compare the Piccard's method with the Newton-Raphson scheme the cavity flow flow problem was computed with quadrilateral elements (Q2Q1). Figure 1 and Figure 2 show that in both cases the solution is stable. As expected, it is hard to see any differences with respect to the accuracy of the results. A distinctive property of the two methods becomes only visible when looking at the convergence plots in Figure 3 where the residual F is plotted against the number of iterations. For the Piccard's scheme a linear relation between the error estimate and the number of iteration can be observed. The Newton-Raphson method on the other hand shows a quadratic behaviour.



Figure 1: Streamlines for the Q2Q1 element obtained with Piccard's (left) and Newton-Raphson (right) scheme



Figure 2: Streamlines for the Q2Q1 element obtained with Piccard's (left) and Newton-Raphson (right) scheme





Figure 3: Convergence plots for the Piccard's scheme (left) and the Newton-Raphson scheme (right)