2D Steady-Unsteady Transport KIMEY WAZARE

2D Steady Unsteady Convention-Diffusion Problem.

A. 2D Steady Transport

Define Problem:

1. A convection-reaction dominated case with

$$||a||=1/2$$
, v=10-4, σ =1.

2. A reaction dominated case with

$$||a||=10-3$$
, v=10-4, $\sigma=1$.

Introduction: To solve the defined problem using formulation such as Galerkin, Streamline Upwind (SU), Streamline Upwind Petrov-Galerkin (SPUG) and Galerkin Least Square (GLS) Method.

Code: The Matlab code for Galerkin, Artificial Diffusion & SUPG was already given and some changes are made in the code to get run GLS method. The changes are as follow,

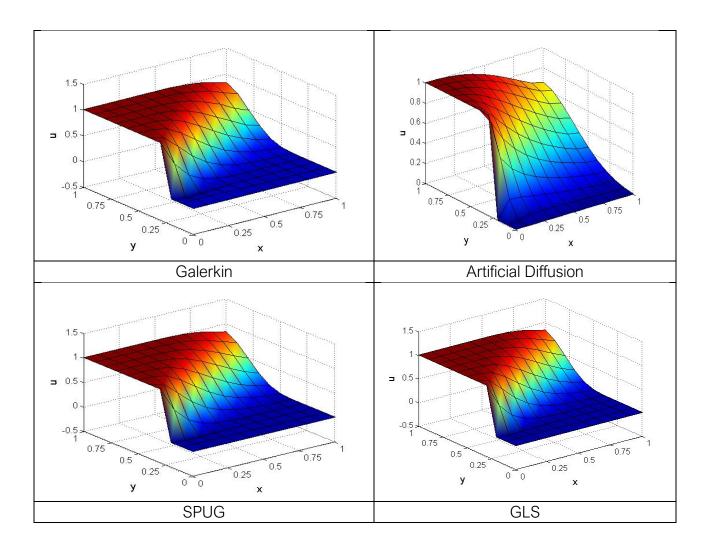
Fig 1: Implementation of GLS method

```
if BC==1
% nodes on which solution is u=1
nodesDirl = nodes_x0( X(nodes_x0,2) > 0.2 );
% nodes on which solution is u=0
nodesDir0 = [nodes_x0(X(nodes_x0,2) \le 0.2); nodes_y0];
% Boundary condition matrix
C = [nodesDirl, ones(length(nodesDirl),1);
     nodesDir0, zeros(length(nodesDir0),1)];
elseif BC==2
% nodes on which solution is u=1
nodesDirl = nodes x0 ( X(nodes x0,2) > 0.2 );
% nodes on which solution is u=0
nodesDir0 = [nodes_x0( X(nodes_x0,2) <= 0.2 ); nodes_y0; nodes_x1; nodes_y1];</pre>
% Boundary condition matrix
C = [nodesDirl, ones(length(nodesDirl),1);
     nodesDir0, zeros(length(nodesDir0),1)];
fprintf('Wrong Boundary Condition option');
```

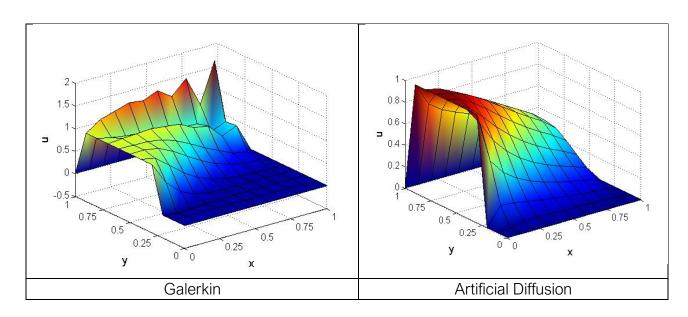
Fig 2: Modification in Boundary Conditions

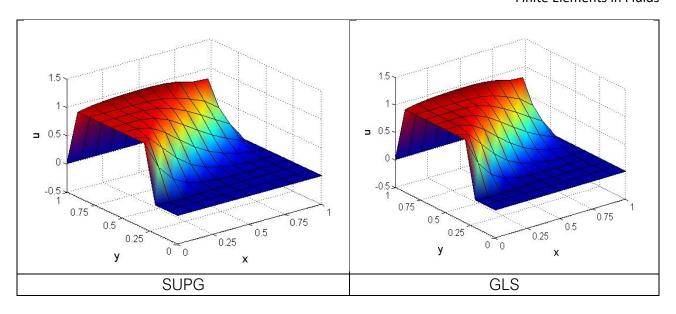
Graphs:

a. Neumann Boundary Condition (σ =0)

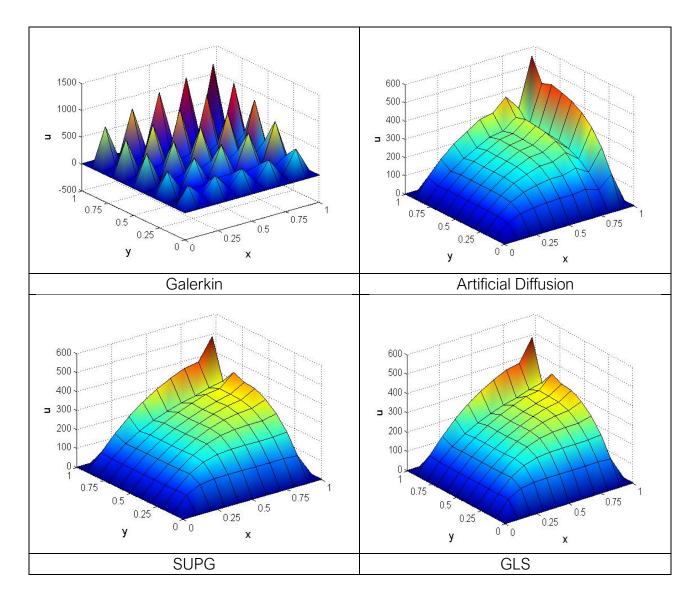


b. Dirichlet Boundary Conditions (σ =0) Galerkin Method produces spurious oscillations, shows instabilities while remaining methods show stability.

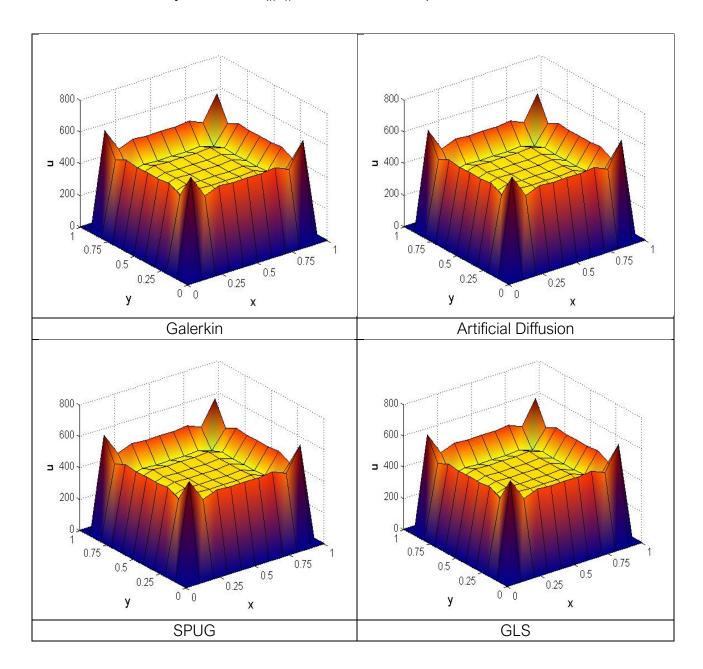




c. Convection-Reaction Dominated Case Dirichlet Boundary Conditions (||a||=1/2, v=10-4, $\sigma=1$), Galerkin method shows instabilities while all other methods are stable.



d. Reaction Dominated Case Dirichlet Boundary Conditions (||a||=10-3, v=10-4, $\sigma=1$), all methods show stabilize results.



B. 2D Unsteady Transport

Define Problem:

2D homogeneous convection equation with initial condition and homogeneous Dirichlet conditions on the inlet boundary

$$U(x,0) = 0.25 * (1 + \cos \pi X_1)(1 + \cos \pi X_2) \qquad \text{if } X_1^2 + X_2^2 \le 1$$

$$U(x,0) = 0$$

Introduction:

The numerical solution has been computed using following finite element schemes:

- i. Lax-Wendroff + Galerkin (and with lumped mass matrix);
- ii. Crank-Nicolson +Galerkin (and lumped mass matrix);
- iii. The third-order explicit Taylor-Galerkin scheme (TG3);
- iv. Two-step third order Taylor-Galerkin-2S method (TG3-2S);
- v. Two-step fourth order Taylor-Galerkin method (TG4-2S).

Code:

The Matlab code for above mentioned methods was already given and some changes are made in the code for TG4-2S method. The changes are as follow,

```
elseif meth == 8
%TG4-2S
    alpha = 1/12;
    Al = M;
    Bl = -(dt/3)*C'- alpha*dt^2*(K - Co);
    fl = (dt/3)*vl + alpha*dt^2*(v2 - vo);
    A2 = M;
    B2 = -dt*C';
    C2 = - (dt^2/2)*(K-Co);
    f2 = dt*vl - (dt^2/2)*(v2 - vo);
else
    error('Unavailable method')
end
```

Fig 1: Implementation of Two-Step Fourth order Taylor-Galerkin Method.

Term Representation in the Supplied Code:

a. Lax-Wendroff Method:

$$\frac{\Delta U}{\Delta t} = -a\nabla U^{n} + \frac{\Delta t}{2}(a\nabla)^{2}U^{n} + s^{n} + \frac{\Delta t}{2}(s_{t}^{n} - a\nabla s^{n})$$
weak form - $(s=0 \text{ Rh}=0)$

$$(\omega, \Delta U) = (a \cdot \nabla \omega, u^{n} - \Delta t (a \cdot \nabla)u^{n}) - (a \cdot n)\omega, u^{n} - \Delta t (a \cdot \nabla)u^{n})_{pout}$$

$$-((a \cdot n)\omega, u^{n} - \Delta t (a \cdot \nabla)u^{n})_{pout}$$

$$+ \text{ teams } \text{ sepresentation} - (\text{supplied code})$$

$$A = T^{n} \rightarrow (\omega, \Delta u)$$

$$B = (C - (\Delta t) \times -m_{0} + (\Delta t)C_{0}) \Delta t$$

$$\text{ i.e. } C = (a \cdot \nabla \omega, u^{n})$$

$$K = (a \cdot \nabla \omega)(a \cdot \nabla u^{n})$$

$$M_{0} = ((a \cdot n)\omega, u^{n})_{pout}$$

$$C_{0} = ((a \cdot n)\omega, (a \cdot \nabla)u^{n})_{pout}$$

b. Crank Nicolson Method:

weak form - (s=0 th=0)

$$(\omega.\Delta u) = \frac{1}{2}(\nabla w.\Delta u) + \frac{1}{2}((\alpha n)w.\Delta u)_{pout} = (\nabla w.\Delta u) - \frac{1}{2}(\nabla w.\Delta u) + \frac{1}{2}((\alpha n)w.\Delta u)_{pout} = (\nabla w.\Delta u) - \frac{1}{2}(\nabla w.\Delta u) + \frac{1}{2}((\alpha n)w.\Delta u)_{pout} = (\nabla w.\Delta u) - \frac{1}{2}(\nabla w.\Delta u) + \frac{1}{2}((\alpha n)w.\Delta u)_{pout} = (\nabla w.\Delta u)$$

$$(\Delta a) = m - (\Delta t) + (\Delta t)$$

c. Third Order Taylor Galerkin Method (TG3):

$$(1 - \frac{\Delta t^{2}}{6}(a \cdot v)^{2}) \frac{\Delta u}{\Delta t} = -a \cdot v u^{n} + \frac{\Delta t}{2}(a \cdot v)^{2} u^{n}$$

$$(u, \frac{\Delta u}{\Delta t}) + \frac{\Delta t^{2}}{6}(a \cdot v u, (a \cdot v \frac{\Delta u}{\Delta t}) - \frac{\Delta t^{2}}{6}((a \cdot n)u, (a \cdot v \frac{\Delta u}{\Delta t}))_{pat} =$$

$$(a \cdot v u, u^{n} - \frac{\Delta t}{2}(a \cdot v) u^{n}) - ((a \cdot n) u, u^{n} - \frac{\Delta t}{2}(a \cdot v) u^{n})_{pat} =$$

$$(a \cdot v u, u^{n} - \frac{\Delta t}{2}(a \cdot v) u^{n}) - ((a \cdot n) u, u^{n} - \frac{\Delta t}{2}(a \cdot v) u^{n})_{pat} =$$

$$(a \cdot v u, u^{n} - \frac{\Delta t^{2}}{6})(k - co)$$

$$(a \cdot v \cdot v \cdot v) = (u \cdot \Delta u)$$

$$(a \cdot v \cdot v) = (u \cdot \Delta u)$$

$$(b \cdot v \cdot v) = ((a \cdot v) u \cdot (a \cdot v) \Delta u)_{pout}$$

$$(b \cdot v) = ((a \cdot v) u \cdot (a \cdot v) \Delta u)_{pout}$$

$$(b \cdot v) = ((a \cdot v) u \cdot (a \cdot v) \Delta u)_{pout}$$

$$(c \cdot v) = ((a \cdot v) u \cdot (a \cdot v) \Delta u)_{pout}$$

$$(e \cdot v) = ((a \cdot v) u \cdot (a \cdot v) \Delta u)_{pout}$$

$$(e \cdot v) = ((a \cdot v) u \cdot (a \cdot v) \Delta u)_{pout}$$

d. Two Step Third Order Taylor Galerkin Method (TG3-2S):

weak form
$$[\alpha = \frac{1}{4}]$$

 $(\omega, \frac{\overline{U}^{n} - U^{n}}{\Delta t}) = \frac{1}{3}(a \cdot \nabla \omega, u^{n}) - \alpha(\Delta t)(a \cdot \nabla \omega, a \cdot \nabla u^{n}) + \alpha(\Delta t)((an)\omega, (a \cdot \nabla)\overline{u}^{n})_{pold}$
 $(\omega, \frac{\overline{U}^{n} - U^{n}}{\Delta t}) = (a \cdot \nabla \omega, u^{n}) - \frac{\Delta t}{2}(a \cdot \nabla \omega, a \cdot \nabla u^{n}) + \frac{\Delta t}{2}((an)\omega, (a \cdot \nabla)\overline{u}^{n})_{pold}$
Here, terms representation in 2 step,
 $A_{1} = [x] \longrightarrow M = (\omega, \overline{u}^{n} - u^{n})$
 $B_{1} = -(\frac{\Delta t}{3})C \longrightarrow \alpha(\Delta t^{2})(K - Co)$
where, $C = (a \cdot \nabla \omega, u^{n})$
 $K = (a \cdot \nabla \omega, a \cdot \nabla u^{n})$
 $A_{2} = [x] \longrightarrow M = (\omega, u^{n+1} - u^{n})$
 $A_{3} = [x] \longrightarrow M = (\omega, u^{n+1} - u^{n})$
 $A_{4} = [x] \longrightarrow M = (\omega, u^{n+1} - u^{n})$
 $A_{5} = [x] \longrightarrow M = (\omega, u^{n+1} - u^{n})$
 $C_{6} = (a \cdot \nabla \omega, a \cdot \nabla u^{n})$
 $C_{7} = (a \cdot \nabla \omega, a \cdot \nabla u^{n})$
 $C_{8} = (a \cdot \nabla \omega, a \cdot \nabla u^{n})$

Graphs: Convection of cosine hill in pure rotation velocity field using finite element schemes.

