# Computational Structural Mechanics and Dynamics 

Assignment 4:
"Iso-P Representation and Iso-P Quadrilateral Elements"

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4.1

- For $N_{1}(\xi)=a_{0}+a_{1}(\xi)+a_{2}(\xi)^{2}$

$$
\begin{array}{r}
N_{1}(0)=a_{0}+a_{1}(0)+a_{2}(0)^{2}=0 \rightarrow a_{0}=0 \\
N_{1}(1)=a_{1}(1)+a_{2}(1)^{2}=0 \rightarrow a_{1}=-a_{2} \\
N_{1}(1)=a_{1}(-1)+a_{2}(-1)^{2}=1 \rightarrow-a_{1}+a_{2}=1 \rightarrow 2 a_{2}=1 \rightarrow a_{2}=\frac{1}{2} \\
a_{1}=-\frac{1}{2} \\
N_{1}(\xi)=-\frac{1}{2}(\xi)+\frac{1}{2}(\xi)^{2}=\frac{1}{2} \xi(\xi-1)
\end{array}
$$

- For $N_{2}(\xi)=b_{0}+b_{1}(\xi)+b_{2}(\xi)^{2}$

$$
\begin{array}{r}
N_{2}(0)=b_{0}+b_{1}(0)+b_{2}(0)^{2} \rightarrow b_{0}=0 \\
N_{2}(-1)=b_{1}(-1)+b_{2}(-1)^{2}=0 \rightarrow b_{1}=b_{2} \\
N_{2}(1)=b_{1}(1)+b_{2}(1)^{2}=1 \rightarrow b_{1}+b_{2}=1 \rightarrow 2 b_{1}=1 \rightarrow b_{1}=\frac{1}{2} \\
b_{2}=\frac{1}{2} \\
N_{2}(\xi)=\frac{1}{2}(\xi)+\frac{1}{2}(\xi)^{2}=\frac{1}{2} \xi(\xi+1)
\end{array}
$$

- For $N_{3}(\xi)=c_{0}+c_{1}(\xi)+c_{2}(\xi)^{2}$

$$
\begin{array}{r}
N_{3}(0)=c_{0}+c_{1}(0)+c_{2}(0)^{2}=1 \rightarrow c_{0}=1 \\
N_{3}(1)=1+c_{1}(1)+c_{2}(1)^{2}=0 \rightarrow c 1_{=}-1-c_{2} \\
N_{3}(-1)=1+c_{1}(-1)+c_{2}(-1)^{2}=0 \rightarrow-c_{1}+c_{2}=-1 \rightarrow 2 c_{2}=-2 \rightarrow c_{2}=-1 \\
c_{1}=0 \\
N_{3}(\xi)=1-\xi^{2}
\end{array}
$$

The sum of the three functions is

$$
N_{1}(\xi)+N_{2}(\xi)+N_{3}(\xi)=\frac{1}{2} \xi^{2}-\frac{1}{2} \xi \frac{1}{2} \xi^{2}+1 / 2 \xi+1 \not-\xi^{2}=1
$$

## 4.2

### 4.2.1.a

From the isoparametric definition of the element we know that:

$$
x=x_{1} N_{1}^{e}+x_{2} N_{2}^{e}+x_{3} N_{3}^{e}
$$

Thus, the position of the nodes and the shape functions are known $x_{1}=0, x_{2}=l, x_{3}=\left(\frac{1}{2}+\alpha\right) l$ and $N_{1}(\xi)=\frac{1}{2} \xi(\xi-1), N_{2}(\xi)=\frac{1}{2} \xi(\xi+1), N_{3}(\xi)=1-\xi^{2}$

$$
\begin{array}{r}
x=l\left(\frac{1}{2} \xi(\xi+1)\right)+\left(\frac{1}{2}+\alpha\right) l\left(1-\xi^{2}\right) \\
x=l\left(\frac{1}{2}+\alpha+\frac{1}{2} \xi-\alpha \xi^{2}\right)
\end{array}
$$

The Jacobian for a 1D element is the derivative of the real coordinate with respect to the normalized one

$$
J=\frac{d x}{d \xi}=l\left(\frac{1}{2}-2 \alpha \xi\right)
$$

As $l$ is always positive, then $\left(\frac{1}{2}-2 \alpha \xi\right)>0$ in order to get $J>0$. Additionally $-1 \leq \xi \leq 1$ as they are the limits of the normalized space. In order to get a positive Jacobian alpha should be bounded between $-\frac{1}{4}$ and $\frac{1}{4}$

### 4.2.1.b

By replacing $\alpha=0$ in the Jacobian expression $J=\frac{d x}{d \xi}=\frac{l}{2}$. It is independent from the point in the normalized space where the Jacobian is evaluated, then it is constant all along the element.

### 4.2.2

The shape functions for the bar are:

$$
\begin{array}{r}
N_{1}(\xi)=\frac{1}{2} \xi(\xi-1) \\
N_{2}(\xi)=\frac{1}{2} \xi(\xi+1) \\
N_{3}(\xi)=1-\xi^{2}
\end{array}
$$

Differentiating with respect to $\xi$ :

$$
\begin{aligned}
& \frac{d N_{1}(\xi)}{d \xi}=\xi-\frac{1}{2} \\
& \frac{d N_{2}(\xi)}{d \xi}=\xi+\frac{1}{2} \\
& \frac{d N_{3}(\xi)}{d \xi}=-2 \xi
\end{aligned}
$$

The inverse of the Jacobian is:

$$
J^{-1}=\frac{d \xi}{d x}=\frac{1}{l(0.5-2 \alpha \xi)}
$$

From the chain rule we can say that $B=\frac{d N}{d x}=\frac{d N}{d \xi} \frac{d \xi}{d x}=\frac{d N}{d \xi} J^{-1}$

$$
B=\frac{1}{l(0.5-2 \alpha \xi)}\left[\begin{array}{c}
\xi-\frac{1}{2} \\
\xi+\frac{1}{2} \\
-2 \xi
\end{array}\right]
$$

## 4.2 .3

The change of coordinates is given by the change of the limits of the integral and the integration parameter. As it is shown in figure 4.2 from the assignment the coordinates $x=0$ and $x=l$ are transformed into $\xi=-1$ and $\xi=1$ in the normalized space.

Also, $J=\frac{d x}{d \xi}$, and multiplying both sides by $d \xi$ we obtain $J d \xi=\frac{d x}{d \xi} d \xi=d x$

## 4.3

The shape functions for a 5 nodded quadrilateral element, take the form of $N_{i}=N_{i}^{l i n e a r}-\alpha N_{5}$, where $\alpha=\frac{1}{4}$

$$
\begin{array}{r}
N_{1}=\frac{1}{4}(1-\xi)(1-\eta)-\frac{1}{4}\left(1-\xi^{2}\right)\left(1-\eta^{2}\right) \\
N_{2}=\frac{1}{4}(1-\xi)(1+\eta)-\frac{1}{4}\left(1-\xi^{2}\right)\left(1-\eta^{2}\right) \\
N_{3}=\frac{1}{4}(1+\xi)(1+\eta)-\frac{1}{4}\left(1-\xi^{2}\right)\left(1-\eta^{2}\right) \\
N_{4}=\frac{1}{4}(1+\xi)(1-\eta)-\frac{1}{4}\left(1-\xi^{2}\right)\left(1-\eta^{2}\right) \\
N_{5}=\left(1-\xi^{2}\right)\left(1-\eta^{2}\right)
\end{array}
$$

As it can be observed in the following graphics, each shape function takes the value of 1 in it's respective node while 0 in the rest. Then, its evident that the sum of the five functions should be equal to 1 if evaluated in any nodal point.


Figure: Shape functions

