

Assignment 4.1

CSMD

Part - 1

$$r_1 = 0, \quad r_2 = r_3 = a, \quad z_1 = z_2 = 0, \quad z_3 = b$$

where $\nu = 0$

Strain-Stress matrix $E = E \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \end{bmatrix} \quad K^e = ?$

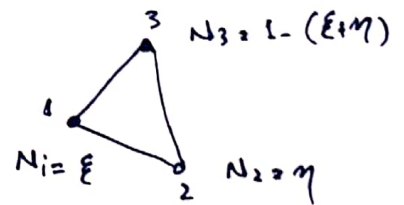
Stiffness matrix can be computed by Numerical Integration by Gauss Rules.

$$K^e = \int_{-1}^1 \int_{-1}^1 h B^T E B \det J \, d\xi \, d\eta \approx \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} w_i w_j F(\xi, \eta)$$

In a more elaborate way for "axisymmetric triangle"

$$K^e = \sum_{i=1}^p \sum_{j=1}^p w_i w_j B^T(\xi_i, \eta_j) E B(\xi_i, \eta_j) r(\xi_i, \eta_j) J(\xi_i, \eta_j) \rightarrow \textcircled{A}$$

where
Shape function $\begin{bmatrix} N_1 \\ N_2 \\ N_3 \end{bmatrix} = \begin{bmatrix} \xi \\ \eta \\ 1 - (\xi + \eta) \end{bmatrix}$



And

$$B = DN = \begin{bmatrix} \frac{\partial}{\partial r} & 0 \\ 0 & \frac{\partial}{\partial z} \\ \frac{1}{r} & 0 \\ \frac{\partial}{\partial z} & \frac{\partial}{\partial r} \end{bmatrix} \begin{bmatrix} N_1^e & 0 & N_2^e & 0 & N_3^e & 0 \\ 0 & N_1^e & 0 & N_2^e & 0 & N_3^e \end{bmatrix} \therefore \begin{bmatrix} N_1^e \\ N_2^e \end{bmatrix} = \begin{bmatrix} \xi \\ \eta \end{bmatrix}$$

$$B = \begin{bmatrix} \frac{\partial N_1}{\partial r} & 0 & \frac{\partial N_2}{\partial r} & 0 & \frac{\partial N_3}{\partial r} & 0 \\ 0 & \frac{\partial N_1}{\partial z} & 0 & \frac{\partial N_2}{\partial z} & 0 & \frac{\partial N_3}{\partial z} \\ \frac{N_1}{r} & 0 & \frac{N_2}{r} & 0 & \frac{N_3}{r} & 0 \\ \frac{\partial N_1}{\partial z} & \frac{\partial N_1}{\partial r} & \frac{\partial N_2}{\partial z} & \frac{\partial N_2}{\partial r} & \frac{\partial N_3}{\partial z} & \frac{\partial N_3}{\partial r} \end{bmatrix}$$

And

$$J = \begin{bmatrix} \frac{\partial r}{\partial \xi} & \frac{\partial z}{\partial \xi} \\ \frac{\partial r}{\partial \eta} & \frac{\partial z}{\partial \eta} \end{bmatrix}$$

(2)

From triangular shape function, we have

$$r = N_1 r_1 + N_2 r_2 + N_3 r$$

$$= \xi(0) + \eta(a) + (1 - (\xi + \eta))a$$

$$\xi \quad z = N_1 z_1 + N_2 z_2 + N_3 z_3$$

$$= \xi(0) + \eta(0) + (1 - (\xi + \eta))(b)$$

$$\boxed{r = a - a\xi}$$

$$\boxed{z = b - b\xi - b\eta}$$

$$\frac{\partial r}{\partial \xi} = -a \quad \xi \quad \frac{\partial r}{\partial \eta} = 0 \quad \xi \quad \frac{\partial z}{\partial \xi} = -b \quad \xi \quad \frac{\partial z}{\partial \eta} = -b \rightarrow (1)$$

$$\text{So, } J = \begin{bmatrix} -a & -b \\ 0 & -b \end{bmatrix} \quad \text{and} \quad J^{-1} = \begin{bmatrix} -\frac{1}{a} & \frac{1}{a} \\ 0 & -\frac{1}{b} \end{bmatrix} = \begin{bmatrix} \frac{\partial \xi}{\partial r} & \frac{\partial \eta}{\partial r} \\ \frac{\partial \xi}{\partial z} & \frac{\partial \eta}{\partial z} \end{bmatrix}$$

$$\frac{\partial \xi}{\partial r} = -\frac{1}{a} \quad \xi \quad \frac{\partial \eta}{\partial r} = \frac{1}{a} \quad \xi \quad \frac{\partial \xi}{\partial z} = 0 \quad \xi \quad \frac{\partial \eta}{\partial z} = -\frac{1}{b} \rightarrow (2)$$

$$\text{As, } \left. \begin{aligned} N_1 = \xi &\Rightarrow \frac{\partial N_1}{\partial \xi} = 1 \quad \xi \quad \frac{\partial N_1}{\partial \eta} = 0 \\ N_2 = \eta &\Rightarrow \frac{\partial N_2}{\partial \xi} = 0 \quad \xi \quad \frac{\partial N_2}{\partial \eta} = 1 \\ N_3 = 1 - (\xi + \eta) &\Rightarrow \frac{\partial N_3}{\partial \xi} = -1 \quad \xi \quad \frac{\partial N_3}{\partial \eta} = -1 \end{aligned} \right\} \rightarrow (3)$$

So, use the values from Eq (1), (2) & (3) to calculate the derivatives of shape function.

$$\frac{\partial N_1}{\partial r} = \frac{\partial N_1}{\partial \xi} \cdot \frac{\partial \xi}{\partial r} + \frac{\partial N_1}{\partial \eta} \cdot \frac{\partial \eta}{\partial r} = (1) \left(-\frac{1}{a}\right) + 0 \left(\frac{1}{a}\right) \Rightarrow \boxed{\frac{\partial N_1}{\partial r} = -\frac{1}{a}}$$

$$\frac{\partial N_1}{\partial z} = \frac{\partial N_1}{\partial \xi} \cdot \frac{\partial \xi}{\partial z} + \frac{\partial N_1}{\partial \eta} \cdot \frac{\partial \eta}{\partial z} = (1)(0) + 0 \left(-\frac{1}{b}\right) \Rightarrow \boxed{\frac{\partial N_1}{\partial z} = 0}$$

$$\frac{\partial N_2}{\partial r} = \frac{\partial N_2}{\partial \xi} \cdot \frac{\partial \xi}{\partial r} + \frac{\partial N_2}{\partial \eta} \cdot \frac{\partial \eta}{\partial r} = (0)\left(-\frac{1}{a}\right) + (1)\left(\frac{1}{a}\right) \Rightarrow \boxed{\frac{\partial N_2}{\partial r} = \frac{1}{a}} \quad (3)$$

$$\frac{\partial N_2}{\partial z} = \frac{\partial N_2}{\partial \xi} \cdot \frac{\partial \xi}{\partial z} + \frac{\partial N_2}{\partial \eta} \cdot \frac{\partial \eta}{\partial z} = (0)(0) + (1)\left(-\frac{1}{b}\right) \Rightarrow \boxed{\frac{\partial N_2}{\partial z} = -\frac{1}{b}}$$

$$\frac{\partial N_3}{\partial r} = \frac{\partial N_3}{\partial \xi} \cdot \frac{\partial \xi}{\partial r} + \frac{\partial N_3}{\partial \eta} \cdot \frac{\partial \eta}{\partial r} = (-1)\left(-\frac{1}{a}\right) + (-1)\left(\frac{1}{a}\right) \Rightarrow \boxed{\frac{\partial N_3}{\partial r} = 0}$$

$$\frac{\partial N_3}{\partial z} = \frac{\partial N_3}{\partial \xi} \cdot \frac{\partial \xi}{\partial z} + \frac{\partial N_3}{\partial \eta} \cdot \frac{\partial \eta}{\partial z} = (-1)(0) + (-1)\left(-\frac{1}{b}\right) \Rightarrow \boxed{\frac{\partial N_3}{\partial z} = \frac{1}{b}}$$

And

$$\boxed{\frac{N_1}{r} = \frac{\xi}{a - a\xi}}$$

$$\boxed{\frac{N_2}{r} = \frac{\eta}{(a - a\xi)}}$$

$$\boxed{\frac{N_3}{r} = \frac{1 - (\xi + \eta)}{a - a\xi}}$$

Put all the entities into B matrix.

$$B = B(\xi_i, \eta_i) = \begin{bmatrix} -\frac{1}{a} & 0 & \frac{1}{a} & 0 & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{b} & 0 & \frac{1}{b} \\ \frac{\xi}{a - a\xi} & 0 & \frac{\eta}{a - a\xi} & 0 & \frac{1 - (\xi + \eta)}{a - a\xi} & 0 \\ 0 & -\frac{1}{a} & -\frac{1}{b} & \frac{1}{a} & \frac{1}{b} & 0 \end{bmatrix}$$

And

$$B^T E B = E \begin{bmatrix} -\frac{1}{a} & 0 & \frac{\xi}{a - a\xi} & 0 \\ 0 & 0 & 0 & -\frac{1}{a} \\ \frac{1}{a} & 0 & \frac{\eta}{a - a\xi} & -\frac{1}{b} \\ 0 & -\frac{1}{b} & 0 & \frac{1}{a} \\ 0 & 0 & \frac{1 - (\xi + \eta)}{a - a\xi} & \frac{1}{b} \\ 0 & \frac{1}{b} & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} -\frac{1}{a} & 0 & \frac{1}{a} & 0 & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{b} & 0 & \frac{1}{b} \\ \frac{\xi}{a - a\xi} & 0 & \frac{\eta}{a - a\xi} & 0 & \frac{1 - (\xi + \eta)}{a - a\xi} & 0 \\ 0 & -\frac{1}{a} & -\frac{1}{b} & \frac{1}{a} & \frac{1}{b} & 0 \end{bmatrix}$$

↓

$$\begin{bmatrix} -\frac{1}{a} & 0 & \frac{1}{a} & 0 & 0 & 0 \\ 0 & 0 & 0 & -\frac{1}{b} & 0 & \frac{1}{b} \\ \frac{\xi}{a - a\xi} & 0 & \frac{\eta}{a - a\xi} & 0 & \frac{1 - (\xi + \eta)}{a - a\xi} & 0 \\ 0 & -\frac{1}{2a} & -\frac{1}{2b} & \frac{1}{2a} & \frac{1}{2b} & 0 \end{bmatrix}$$

$$B^T E B = E \begin{bmatrix} \frac{1}{a^2} + \frac{\xi^2}{(a-a\xi)^2} & 0 & -\frac{1}{a^2} + \frac{\xi\eta}{(a-a\xi)^2} & 0 & \frac{\xi(1-(\xi+\eta))}{(a-a\xi)^2} & 0 \\ 0 & \frac{1}{2a^2} & \frac{1}{2ab} & -\frac{1}{2a^2} & -\frac{1}{2ab} & 0 \\ -\frac{1}{a^2} + \frac{\xi\eta}{(a-a\xi)^2} & \frac{1}{2ab} & \frac{1}{a^2} + \frac{\eta^2}{(a-a\xi)^2} + \frac{1}{2b^2} & -\frac{1}{2ab} & \frac{\eta(1-(\xi+\eta))}{(a-a\xi)^2} - \frac{1}{2b^2} & 0 \\ 0 & -\frac{1}{2a^2} & -\frac{1}{2ab} & \frac{1}{b^2} + \frac{1}{2a^2} & \frac{1}{2ab} & -\frac{1}{b^2} \\ \frac{\xi(1-(\xi+\eta))}{(a-a\xi)^2} & -\frac{1}{2ab} & \frac{\eta(1-(\xi+\eta))}{(a-a\xi)^2} - \frac{1}{2b^2} & \frac{1}{2ab} & \frac{(1-(\xi+\eta))^2}{(a-a\xi)^2} + \frac{1}{2b^2} & 0 \\ 0 & 0 & 0 & -\frac{1}{b^2} & 0 & \frac{1}{b^2} \end{bmatrix} \quad (4)$$

Put in Eq (4) and Applying Gauss Quadrature (1 point) with $\xi = \frac{1}{3}$, $\eta = \frac{1}{3}$
and $\det J = |J| = ab$ and $w_i = w_j = 1$

So K^e matrix will be

$$K^e = \frac{2}{3} E a^2 b \begin{bmatrix} \frac{1}{a^2} + \frac{1}{4a^2} & 0 & -\frac{1}{a^2} + \frac{1}{4a^2} & 0 & \frac{1}{4a^2} & 0 \\ 0 & \frac{1}{2a^2} & \frac{1}{2ab} & -\frac{1}{2a^2} & -\frac{1}{2ab} & 0 \\ -\frac{1}{a^2} + \frac{1}{4a^2} & \frac{1}{2ab} & \frac{1}{a^2} + \frac{1}{4a^2} + \frac{1}{2b^2} & -\frac{1}{2ab} & \frac{1}{4a^2} - \frac{1}{2b^2} & 0 \\ 0 & -\frac{1}{2a^2} & -\frac{1}{2ab} & \frac{1}{b^2} + \frac{1}{2a^2} & \frac{1}{2ab} & -\frac{1}{b^2} \\ \frac{1}{4a^2} & -\frac{1}{2ab} & \frac{1}{4a^2} - \frac{1}{2b^2} & \frac{1}{2ab} & \frac{1}{4a^2} + \frac{1}{2b^2} & 0 \\ 0 & 0 & 0 & -\frac{1}{b^2} & 0 & \frac{1}{b^2} \end{bmatrix}$$

(Part-2)

$$R-2 = \frac{1}{2a^2} + \frac{1}{2ab} - \frac{1}{2a^2} - \frac{1}{2ab} = 0$$

⑤

$$R-4 = -\frac{1}{2a^2} - \frac{1}{2ab} + \frac{1}{b^2} + \frac{1}{2a^2} + \frac{1}{2ab} - \frac{1}{b^2} = 0$$

$$R-6 = -\frac{1}{b^2} + \frac{1}{b^2} = 0$$

E₃

$$C-2 = +\frac{1}{2a^2} + \frac{1}{2ab} - \frac{1}{2a^2} - \frac{1}{2ab} = 0$$

$$C-4 = -\frac{1}{2a^2} - \frac{1}{2ab} + \frac{1}{b^2} + \frac{1}{2a^2} + \frac{1}{2ab} - \frac{1}{b^2} = 0$$

$$C-6 = -\frac{1}{b^2} + \frac{1}{b^2} = 0$$

Now

$$R-1 = \frac{1}{a^2} + \frac{1}{4a^2} - \frac{1}{a^2} + \frac{1}{4a^2} + \frac{1}{4a^2} \neq 0$$

$$R-3 = -\frac{1}{a^2} + \frac{1}{4a^2} + \frac{1}{2ab} + \frac{1}{a^2} + \frac{1}{4a^2} + \frac{1}{2b^2} - \frac{1}{2ab} + \frac{1}{4a^2} - \frac{1}{2b^2} \neq 0$$

$$R-5 = \frac{1}{4a^2} - \frac{1}{2ab} + \frac{1}{4a^2} - \frac{1}{2b^2} + \frac{1}{2ab} + \frac{1}{4a^2} + \frac{1}{2b^2} \neq 0$$

E₄

$$C-1 = \frac{1}{a^2} + \frac{1}{4a^2} - \frac{1}{a^2} + \frac{1}{4a^2} + \frac{1}{4a^2} \neq 0$$

$$C-3 = -\frac{1}{a^2} + \frac{1}{4a^2} + \frac{1}{2ab} + \frac{1}{a^2} + \frac{1}{4a^2} + \frac{1}{2b^2} - \frac{1}{2ab} + \frac{1}{4a^2} - \frac{1}{2b^2} \neq 0$$

$$C-5 = \frac{1}{4a^2} - \frac{1}{2ab} + \frac{1}{4a^2} - \frac{1}{2b^2} + \frac{1}{2ab} + \frac{1}{4a^2} + \frac{1}{2b^2} \neq 0$$

Comments :-

It is cleared that rows and columns which contain q_r ($\frac{N_i}{Y}$) entities are not summed up to zero. The extra term from axisymmetry create non-singularity and make calculation complex. While the rows and columns which do not share ' q_r ' entities are summed up to zero.

part-3

②

As Consistent force vector is

$$f^e = \sum_{i=1}^p \sum_{j=1}^p w_i w_j N^T(\xi_i, \eta_j) b(\xi_i, \eta_j) r(\xi_i, \eta_j) \det J(\xi_i, \eta_j)$$

$$\text{As } b = \begin{bmatrix} 0 \\ -q \end{bmatrix}, \quad N = \begin{bmatrix} N_1 & 0 & N_2 & 0 & N_3 & 0 \\ 0 & N_1 & 0 & N_2 & 0 & N_3 \end{bmatrix}$$

$$N^T = \begin{bmatrix} N_1 & 0 \\ 0 & N_1 \\ N_2 & 0 \\ 0 & N_2 \\ N_3 & 0 \\ 0 & N_3 \end{bmatrix} = \begin{bmatrix} \xi & 0 \\ 0 & \xi \\ \eta & 0 \\ 0 & \eta \\ 1-(\xi+\eta) & 0 \\ 0 & 1-(\xi+\eta) \end{bmatrix}$$

take $w_i w_j = 1$ and $\xi = \frac{1}{3} = \eta$ and $|J| = ab$

$$r = \frac{2a}{3}$$

$$f^e = \frac{2}{3} a^2 b \begin{bmatrix} 1/3 & 0 \\ 0 & 1/3 \\ 1/3 & 0 \\ 0 & 1/3 \\ 1/3 & 0 \\ 0 & 1/3 \end{bmatrix} \begin{bmatrix} 0 \\ -q \end{bmatrix} = \frac{2}{3} a^2 b \begin{bmatrix} 0 \\ -q/3 \\ 0 \\ -q/3 \\ 0 \\ -q/3 \end{bmatrix}$$

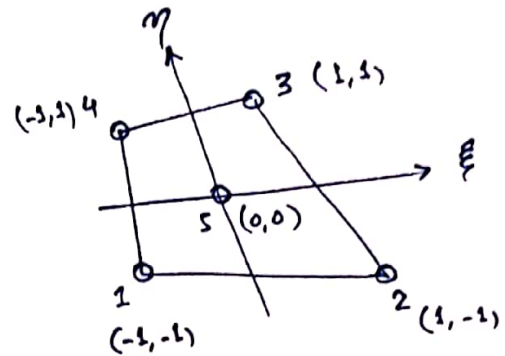
Assignment. No. 4.2

(7)

Five Shape Function of

Quadrilateral

N_1, N_2, N_3, N_4, N_5



Shape Function for $i = 1, 2, 3, 4$ can be calculated by $N_i = N_i + \alpha N_5$ while N_5 through line-product method.

So

$$N_5 = \alpha L_{1-2} L_{2-3} L_{3-4} L_{4-1}$$

$$N_5 = \alpha (1+\eta)(1-\xi)(1-\eta)(1+\xi)$$

$$N_5 = \alpha (1-\eta^2)(1-\xi^2)$$

$$N_5 = \alpha (1-\xi^2)(1-\eta^2)$$

For $\alpha = 1$ at mode 5

$$N_5 = 1 \text{ and } N_1 = N_2 = N_3 = N_4 = 0$$

For corner nodes 1, 2, 3, 4

$$N_1 = c (1-\xi)(1-\eta)(\xi)(\eta)$$

$$N_2 = c (1+\xi)(1-\eta)(\xi)(\eta)$$

$$N_3 = c (1+\xi)(1+\eta)(\xi)(\eta)$$

$$N_4 = c (1-\xi)(1+\eta)(\xi)(\eta)$$

For $c = 1/4$ at $i = 1, 2, 3, 4$

$$N_1 = N_2 = N_3 = N_4 = 1 \text{ and } N_5 = 0$$

$i = \quad 1 \quad 2 \quad 3 \quad 4$