

Master of Science in Computational Mechanics 2018
Computational Structural Mechanics and Dynamics

“Structures of revolution”

Assignment 4.1

1. Compute the entries of \mathbf{K}^e for the following axisymmetric triangle:

$$r_1 = 0, \quad r_2 = r_3 = a, \quad z_1 = z_2 = 0, \quad z_3 = b$$

The material is isotropic with $\nu = 0$ for which the stress-strain matrix is,

$$\mathbf{E} = E \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \end{bmatrix}$$

2. Show that the sum of the rows (and columns) 2, 4 and 6 of \mathbf{K}^e must vanish and explain why. Show as well that the sum of rows (and columns) 1, 3 and 5 does not vanish, and explain why.
3. Compute the consistent force vector \mathbf{f}^e for gravity forces $\mathbf{b} = [0, -g]^T$.

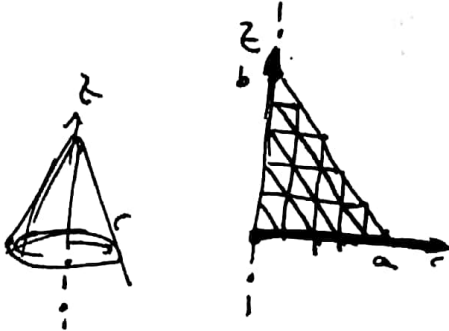
Date of Assignment: 26 / 02 / 2018

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The assignment must be submitted as a pdf file named **As4-Surname.pdf** to the CIMNE virtual center.

Assignment 4.1

$$1 - \begin{cases} r_1 = 0 \\ r_2 = r_3 = a \\ E_1 = E_2 = 0 \\ E_3 = b \end{cases}$$



Axisymmetric triangle

$$E = \begin{bmatrix} E_{11} & E_{12} & E_{13} & E_{14} \\ E_{12} & E_{22} & E_{23} & E_{24} \\ E_{13} & E_{23} & E_{33} & 0 \\ E_{14} & E_{24} & 0 & E_{44} \end{bmatrix} \xrightarrow{\text{isotropic}} \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & \nu & 0 \\ \nu & 1-\nu & \nu & 0 \\ 0 & \nu & \nu & 1-2\nu \\ 0 & 0 & 0 & \frac{1}{2}(1-2\nu) \end{bmatrix} \xrightarrow{\nu=0} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1/2 \end{bmatrix}$$

$$N = \begin{bmatrix} N_1^e & N_2^e & \dots & N_n^e & 0 & 0 & 0 & 0 \\ 0 & 0 & \dots & 0 & N_1^e & N_2^e & \dots & 0 \end{bmatrix}$$

$$\begin{cases} E_{11} = E_{22} = E_{33} = 1 \\ E_{44} = 1/2 \end{cases}$$

$B = DN$

$$B = \begin{bmatrix} q_r & 0 \\ 0 & q_\theta \\ q_z & q_r \end{bmatrix} \begin{cases} q_r = \begin{bmatrix} \frac{du}{dr} & \frac{dv}{dr} & \frac{dw}{dr} & \dots & \frac{dN_1}{dr} \end{bmatrix} \\ q_\theta = \begin{bmatrix} \frac{dv}{r} & \frac{dw}{r} & \dots & \frac{dN_2}{r} \end{bmatrix} \\ q_z = \begin{bmatrix} \frac{dw}{dz} & \dots & \frac{dN_3}{dz} \end{bmatrix} \end{cases} \xrightarrow{\text{side length deriv}} \begin{cases} \left[\frac{du}{dr}, \frac{dv}{r}, \frac{dw}{dz} \right] \\ \left[\frac{dv}{r}, \frac{dw}{r}, \dots \right] \\ \left[\frac{dw}{dz}, \dots, \frac{dN_3}{dz} \right] \end{cases}$$

$$EB = \begin{bmatrix} q_r & 0 \\ q_\theta & 0 \\ \frac{q_z}{2} & \frac{q_r}{2} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \\ C_{31} & C_{32} \\ C_{41} & C_{42} \end{bmatrix}$$

$B^T E B = \begin{bmatrix} S_{rr} & S_{rz} \\ S_{zr} & S_{zz} \end{bmatrix}$ (6x6) \leftarrow vertical & hor. for each node of the element

$$\begin{cases} S_{rr} = q_r^T C_{11} + q_\theta^T C_{21} + q_z^T C_{31} \\ S_{rz} = S_{zr} = q_r^T C_{41} + q_\theta^T C_{42} + q_z^T C_{43} \\ S_{zz} = q_r^T C_{41} + q_\theta^T C_{42} \end{cases} \rightarrow \begin{cases} S_{rr}^{e1} = q_r^T q_r + q_\theta^T q_\theta + q_z^T \frac{q_z}{2} \\ S_{rz}^{e1} = S_{zr}^{e1} = q_r^T \frac{q_z}{2} \\ S_{zz}^{e1} = q_r^T \frac{q_z}{2} + q_\theta^T q_\theta \end{cases}$$

$$S_{rr}^{e1} = \begin{pmatrix} \frac{du}{dr} \\ \frac{dv}{r} \\ \frac{dw}{dz} \end{pmatrix} \begin{pmatrix} \frac{du}{dr} & \frac{dv}{r} & \frac{dw}{dz} \end{pmatrix} + \begin{pmatrix} \frac{N_1}{r} \\ \frac{N_2}{r} \\ \frac{N_3}{r} \end{pmatrix} \begin{pmatrix} \frac{N_1}{r} & \frac{N_2}{r} & \frac{N_3}{r} \end{pmatrix} + \begin{pmatrix} \frac{du}{dr} \\ \frac{dv}{r} \\ \frac{dw}{dz} \end{pmatrix} \begin{pmatrix} \frac{du}{dr} & \frac{dv}{r} & \frac{dw}{dz} \end{pmatrix} =$$

$$= \begin{bmatrix} \left(\frac{du}{dr}\right)^2 & \frac{du}{dr} \frac{dv}{r} & \frac{du}{dr} \frac{dw}{dz} \\ \frac{du}{dr} \frac{dv}{r} & \left(\frac{dv}{r}\right)^2 & \frac{dv}{r} \frac{dw}{dz} \\ \frac{du}{dr} \frac{dw}{dz} & \frac{dv}{r} \frac{dw}{dz} & \left(\frac{dw}{dz}\right)^2 \end{bmatrix} + \begin{bmatrix} \frac{N_1^2}{r^2} & \frac{N_1 N_2}{r^2} & \frac{N_1 N_3}{r^2} \\ \frac{N_2 N_1}{r^2} & \frac{N_2^2}{r^2} & \frac{N_2 N_3}{r^2} \\ \frac{N_3 N_1}{r^2} & \frac{N_3 N_2}{r^2} & \frac{N_3^2}{r^2} \end{bmatrix} + \frac{1}{2} \begin{bmatrix} \left(\frac{du}{dr}\right)^2 & \frac{du}{dr} \frac{dv}{r} & \frac{du}{dr} \frac{dw}{dz} \\ \frac{du}{dr} \frac{dv}{r} & \left(\frac{dv}{r}\right)^2 & \frac{dv}{r} \frac{dw}{dz} \\ \frac{du}{dr} \frac{dw}{dz} & \frac{dv}{r} \frac{dw}{dz} & \left(\frac{dw}{dz}\right)^2 \end{bmatrix}$$

$$e) \quad E S_{zz} = \frac{1}{2} \begin{pmatrix} \frac{\partial u_1}{\partial x} \\ \frac{\partial u_2}{\partial x} \\ \frac{\partial u_3}{\partial x} \end{pmatrix} \begin{pmatrix} \frac{\partial u_1}{\partial x} & \frac{\partial u_2}{\partial x} & \frac{\partial u_3}{\partial x} \end{pmatrix} = \frac{1}{2} \begin{bmatrix} \frac{\partial u_1}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_1}{\partial x} \frac{\partial u_2}{\partial x} & \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} \\ \frac{\partial u_2}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_2}{\partial x} \frac{\partial u_2}{\partial x} & \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} \\ \frac{\partial u_3}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_3}{\partial x} \frac{\partial u_2}{\partial x} & \frac{\partial u_3}{\partial x} \frac{\partial u_3}{\partial x} \end{bmatrix}$$

$$e) \quad E S_{zz} = \frac{1}{2} \begin{bmatrix} \left(\frac{\partial u_1}{\partial x}\right)^2 & \frac{\partial u_1}{\partial x} \frac{\partial u_2}{\partial x} & \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} \\ \frac{\partial u_2}{\partial x} \frac{\partial u_1}{\partial x} & \left(\frac{\partial u_2}{\partial x}\right)^2 & \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} \\ \frac{\partial u_3}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_3}{\partial x} \frac{\partial u_2}{\partial x} & \left(\frac{\partial u_3}{\partial x}\right)^2 \end{bmatrix} + \begin{bmatrix} \frac{\partial u_1}{\partial x} \frac{\partial u_2}{\partial x} & \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} & \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} \\ \frac{\partial u_2}{\partial x} \frac{\partial u_1}{\partial x} & \left(\frac{\partial u_2}{\partial x}\right)^2 & \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} \\ \frac{\partial u_3}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_3}{\partial x} \frac{\partial u_2}{\partial x} & \left(\frac{\partial u_3}{\partial x}\right)^2 \end{bmatrix}$$

$$e) \quad B^T E B = \begin{bmatrix} \left(\frac{\partial u_1}{\partial x}\right)^2 + \left(\frac{\partial u_2}{\partial x}\right)^2 + \left(\frac{\partial u_3}{\partial x}\right)^2 & \frac{\partial u_1}{\partial x} \frac{\partial u_2}{\partial x} + \frac{\partial u_2}{\partial x} \frac{\partial u_1}{\partial x} + \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} + \frac{\partial u_3}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} + \frac{\partial u_3}{\partial x} \frac{\partial u_2}{\partial x} \\ \frac{\partial u_2}{\partial x} \frac{\partial u_1}{\partial x} + \frac{\partial u_1}{\partial x} \frac{\partial u_2}{\partial x} + \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} + \frac{\partial u_3}{\partial x} \frac{\partial u_2}{\partial x} & \left(\frac{\partial u_2}{\partial x}\right)^2 + \left(\frac{\partial u_3}{\partial x}\right)^2 & \frac{\partial u_2}{\partial x} \frac{\partial u_1}{\partial x} + \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} + \frac{\partial u_3}{\partial x} \frac{\partial u_1}{\partial x} \\ \frac{\partial u_3}{\partial x} \frac{\partial u_1}{\partial x} + \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} + \frac{\partial u_3}{\partial x} \frac{\partial u_2}{\partial x} + \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} & \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} + \frac{\partial u_3}{\partial x} \frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} + \frac{\partial u_3}{\partial x} \frac{\partial u_2}{\partial x} & \left(\frac{\partial u_3}{\partial x}\right)^2 + \left(\frac{\partial u_2}{\partial x}\right)^2 \\ \frac{\partial u_1}{\partial x} \frac{\partial u_2}{\partial x} & \frac{\partial u_2}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} \\ \frac{\partial u_2}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_1}{\partial x} \frac{\partial u_2}{\partial x} & \frac{\partial u_2}{\partial x} \frac{\partial u_3}{\partial x} \\ \frac{\partial u_3}{\partial x} \frac{\partial u_1}{\partial x} & \frac{\partial u_1}{\partial x} \frac{\partial u_3}{\partial x} & \frac{\partial u_3}{\partial x} \frac{\partial u_2}{\partial x} \end{bmatrix}$$

if linear triangle element

$$\begin{cases} N_1 = \frac{E_1}{E} = \frac{x}{L} \\ N_2 = \frac{E_2}{E} = \frac{y}{L} \\ N_3 = \frac{E_3}{E} = 1 - (x/L) - (y/L) \end{cases}$$

isoparametric linear triangle

$$K = 2\pi \int_A B^T E B dA$$

$$\begin{cases} \frac{\partial \xi_i}{\partial x} = \frac{b_i}{2A^c} \\ \frac{\partial \xi_i}{\partial y} = \frac{c_i}{2A^c} \end{cases} \begin{cases} b_i = y_j - y_k \\ c_i = x_k - x_j \end{cases}$$

isoparametric coordinates

$$\begin{aligned} \frac{\partial N_1}{\partial x} &= \frac{1}{L} & \frac{\partial N_2}{\partial x} &= \frac{1}{L} \\ \frac{\partial N_1}{\partial y} &= \frac{1}{L} & \frac{\partial N_2}{\partial y} &= \frac{1}{L} \\ \frac{\partial N_3}{\partial x} &= -\frac{1}{L} & \frac{\partial N_3}{\partial y} &= -\frac{1}{L} \end{aligned}$$

3 - Compute consistent force f^e
for $b = [c, -g]^T$

$$f^e = \int_A N^T b \, r \, dA = \int_A \begin{bmatrix} N_1^e c \\ N_2^e c \\ N_3^e c \\ 0 \\ 0 \\ 0 \\ -N_1^e g \\ -N_2^e g \\ -N_3^e g \end{bmatrix} [-g] \, dA = \int_A \begin{bmatrix} 0 \\ 0 \\ 0 \\ -N_1^e g \\ -N_2^e g \\ -N_3^e g \end{bmatrix} dA = -g \int_A \begin{bmatrix} 0 \\ 0 \\ 0 \\ N_1^e \\ N_2^e \\ N_3^e \end{bmatrix} dA$$

$$N^e = \begin{bmatrix} N_1^e & N_2^e & N_3^e & 0 & 0 & 0 \\ 0 & 0 & 0 & N_1^e & N_2^e & N_3^e \end{bmatrix}$$

$$f^e = -g \begin{bmatrix} 0 \\ 0 \\ 0 \\ \int N_1^e dA \\ \int N_2^e dA \\ \int N_3^e dA \end{bmatrix} = -g \begin{bmatrix} 0 \\ 0 \\ 0 \\ \int \xi_1 dA \\ \int \xi_2 dA \\ \int \xi_3 dA \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ \int \xi_1 dA \\ \int \xi_2 dA \\ \int \xi_3 dA \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ -g \frac{1}{3} A^e \\ -g \frac{1}{3} A^e \\ -g \frac{1}{3} A^e \end{bmatrix}$$

$$A^e = \frac{a \cdot b}{2}$$

N = number of elements.

degree 1

$$\frac{1}{A^e} \int_A F(\xi_1, \xi_2, \xi_3) \, dA \approx F\left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$$

$$\int F(\xi_1, \xi_2, \xi_3) \, dA \approx A^e \left[\frac{1}{3} \right]$$