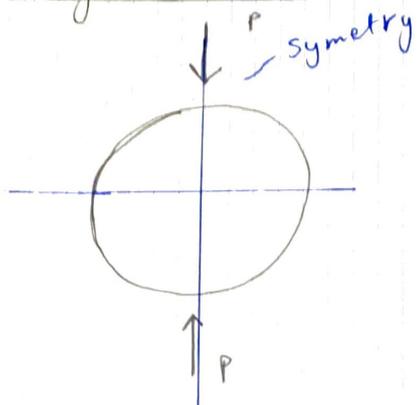


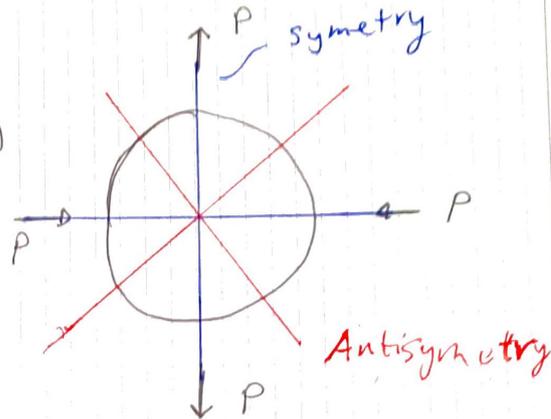
Nicolas Grönland  
Assignment 2.1

1)

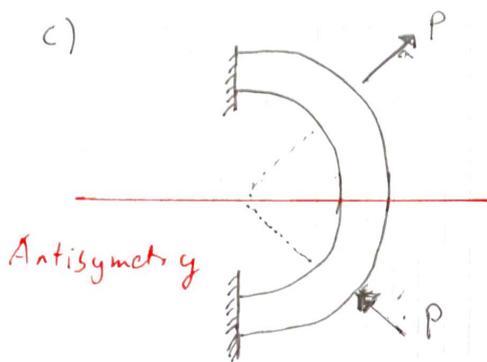
a)



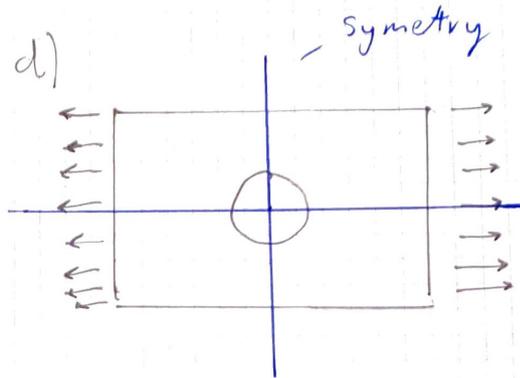
b)



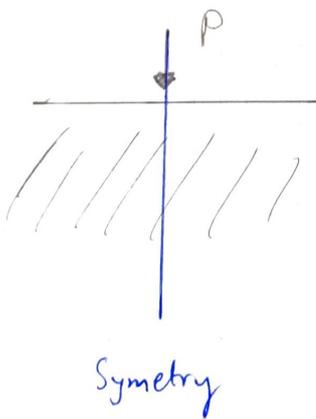
c)



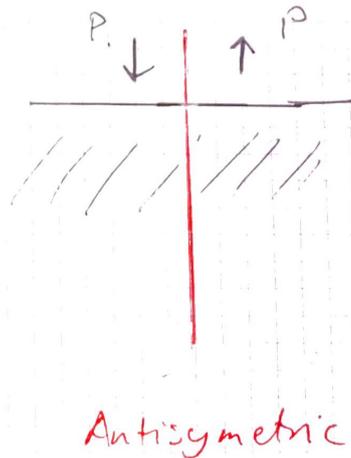
d)

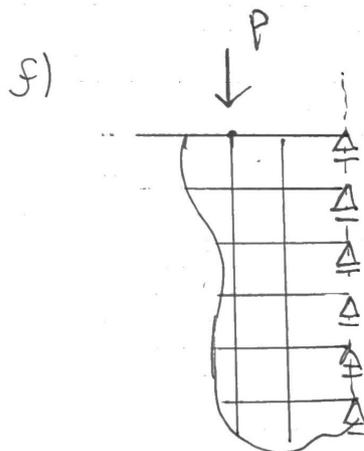
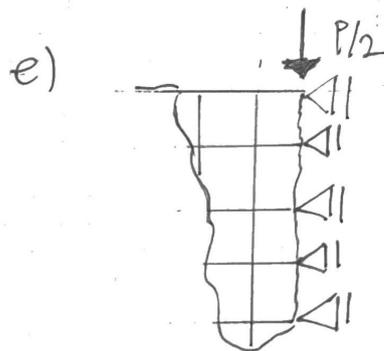
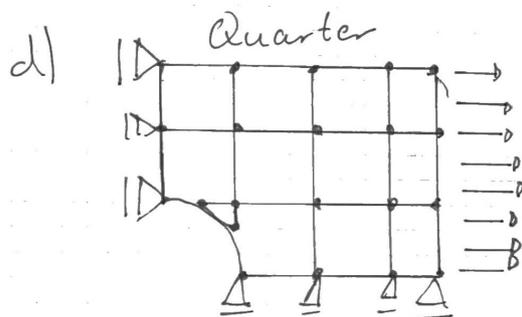
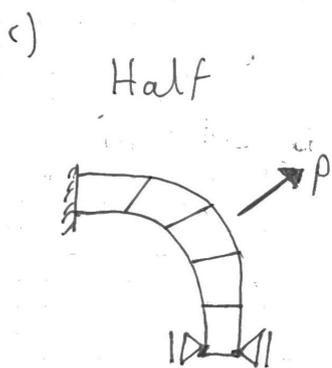
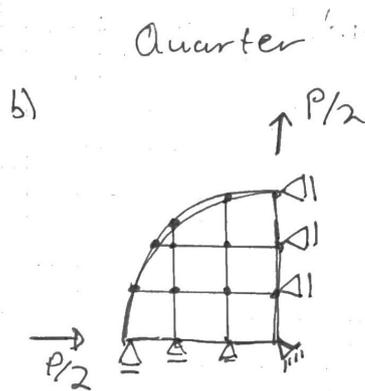
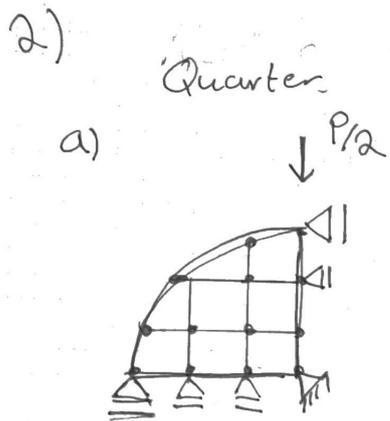


e)



f)





For c) the force on the other side of the a-symmetry line will prevent horizontal movement.

For f) we have the same argument, but here vertical movement is prevented.

## Assignment 2.2.

- Verification is about the checking process that should be done when using FEM.

This means:

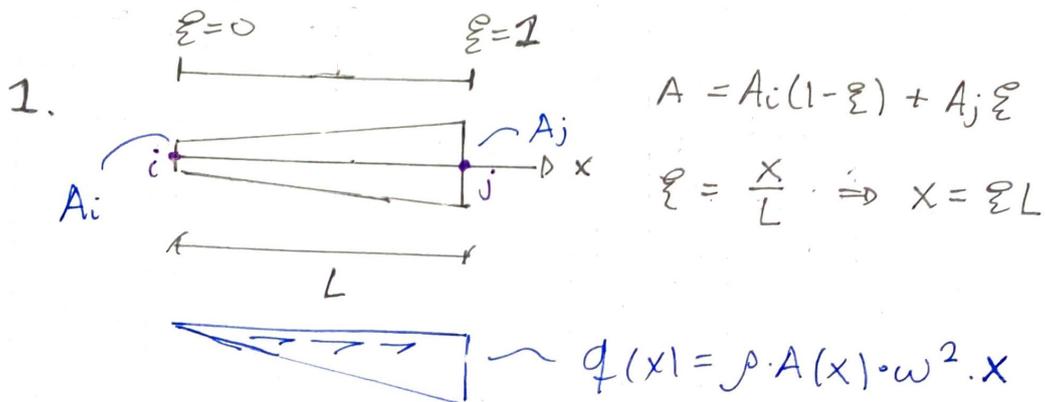
- Making sure it works
- Getting the math right
- Providing an accurate analysis.

⇒ Does your analysis accurately represent the mathematical problem that you have formulated.

- On the other hand validation is about checking if the analysis coincide with available data.

⇒ Is the analysis a correct representation of the physics and the actual physical problem.

## Assignment 2.3



Transforming everything to natural coordinates:

$$A = A_i(1-\xi) + A_j \cdot \xi$$

$$q(\xi) = \rho \cdot \omega^2 \cdot A(\xi) \cdot \xi \cdot L$$

$$\frac{dx}{d\xi} = L \Rightarrow dx = d\xi \cdot L$$

Consistent nodal force vector:

$$F_{ext} = \int_0^L q(x) \cdot N(x) dx$$

Defining shape functions based on natural coordinates:

$$N_i(\xi) = 1 - \xi$$

$$N_j(\xi) = \xi$$

$$\Rightarrow F_{\text{ext}} = \int_0^L q(x) N(x) dx$$

$$= \int_0^1 q(\xi) \cdot N(\xi) \cdot L \cdot d\xi$$

$$= \int_0^1 \rho \cdot \omega^2 \cdot L \cdot \xi (A_i (1-\xi) + A_j \cdot \xi) \cdot \begin{bmatrix} 1-\xi \\ \xi \end{bmatrix} \cdot L \cdot d\xi$$

$$= \rho \cdot \omega^2 \cdot L^2 \int_0^1 (A_i (\xi - \xi^2) + A_j \cdot \xi^2) \begin{bmatrix} 1-\xi \\ \xi \end{bmatrix} d\xi$$

$$= \rho \cdot \omega^2 \cdot L^2 \int_0^1 \begin{bmatrix} A_i (\xi - \xi^2)(1-\xi) + A_j \xi^2(1-\xi) \\ A_i (\xi^2 - \xi^3) + A_j \xi^3 \end{bmatrix} d\xi$$

$$= \rho \omega^2 \cdot L^2 \int_0^1 \begin{bmatrix} A_i (\xi - \xi^2 - \xi^2 + \xi^3) + A_j (\xi^2 - \xi^3) \\ A_i (\xi^2 - \xi^3) + A_j \xi^3 \end{bmatrix} d\xi$$

$$= \rho \cdot \omega^2 \cdot L^2 \begin{bmatrix} A_i \left( \frac{1}{2} - 2 \cdot \frac{1}{3} + \frac{1}{4} \right) + A_j \left( \frac{1}{3} - \frac{1}{4} \right) \\ A_i \left( \frac{1}{3} - \frac{1}{4} \right) + A_j \cdot \frac{1}{4} \end{bmatrix}$$

$$= \rho \cdot \omega^2 \cdot L^2 \begin{bmatrix} A_i \cdot \frac{1}{12} + A_j \cdot \frac{1}{12} \\ A_i \cdot \frac{1}{12} + A_j \cdot \frac{1}{4} \end{bmatrix} = \begin{bmatrix} f_{\text{ext},1} \\ f_{\text{ext},2} \end{bmatrix}$$

Specializing the result to  $A_i = A_j = A$  :

$$\Rightarrow F_{\text{ext}} = \rho \cdot \omega^2 \cdot L^2 \cdot A \begin{bmatrix} 1/12 + 1/12 \\ 1/12 + 1/4 \end{bmatrix}$$

$$= \rho \cdot \omega^2 \cdot L^2 \cdot A \begin{bmatrix} 1/6 \\ 1/3 \end{bmatrix}$$

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