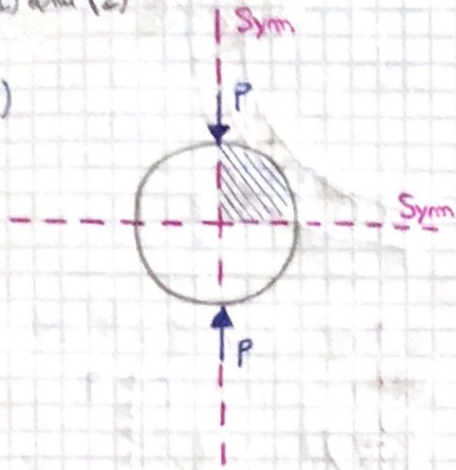


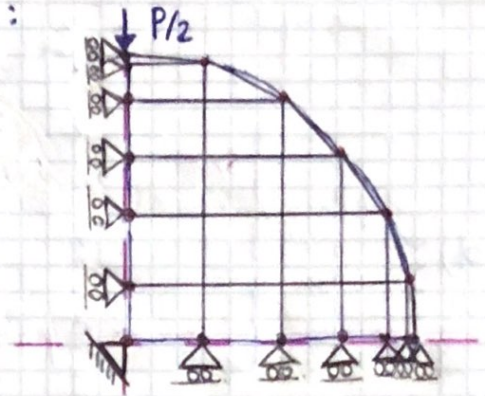
Assignment 2.1

(1) and (2)

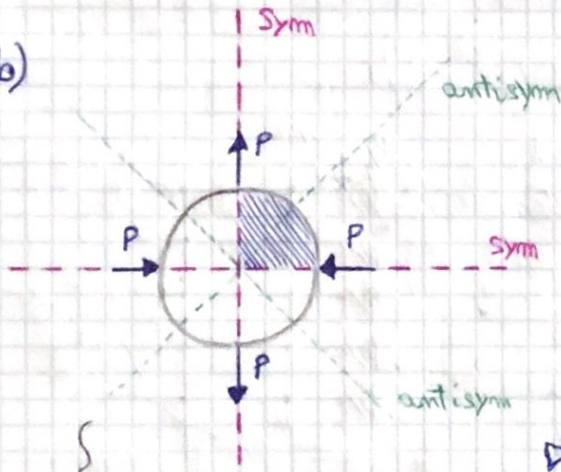
a)



It's possible to cut the structure to one quarter:

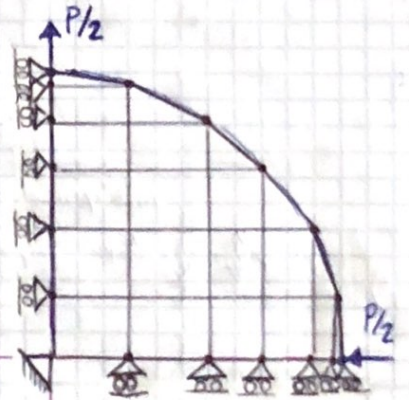


b)



It's possible to cut the structure to one quarter:

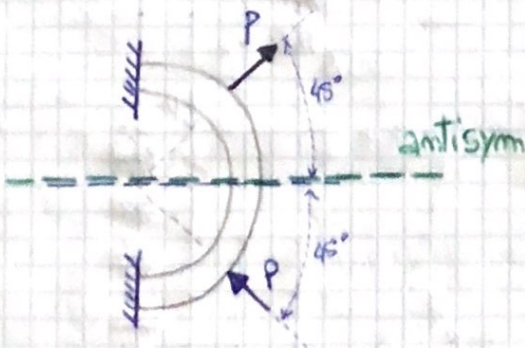
or



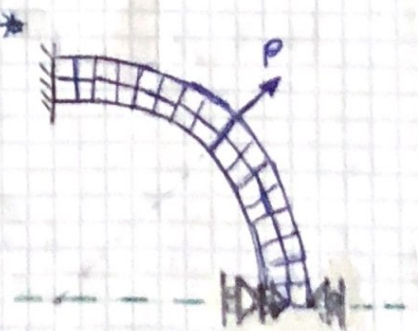
Here there are two antisymmetric lines too. So I could model it as divided in 8 parts and focus only on one of them. FE.:



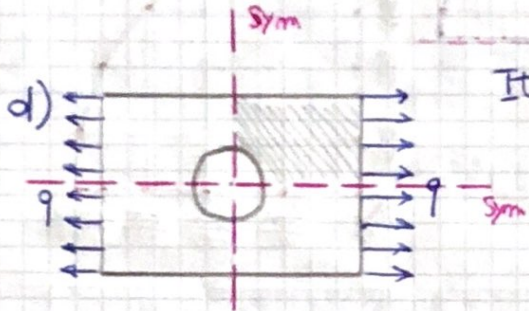
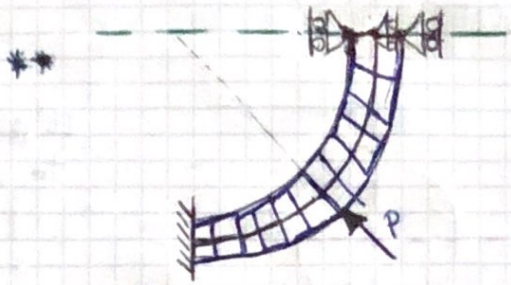
c)



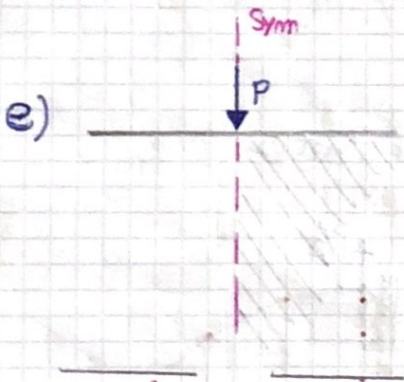
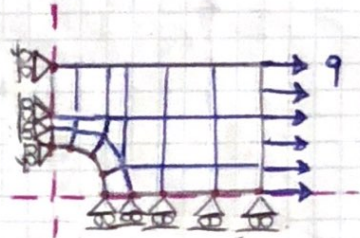
It's possible to cut the structure to one half:



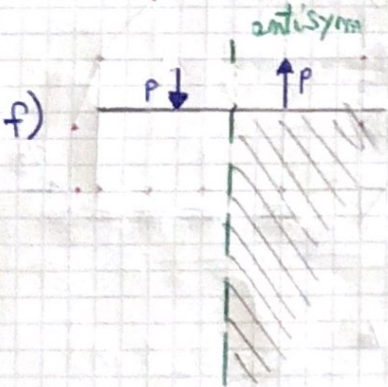
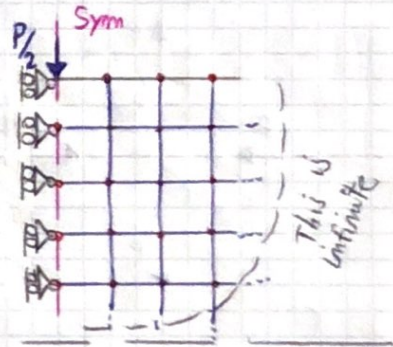
or:



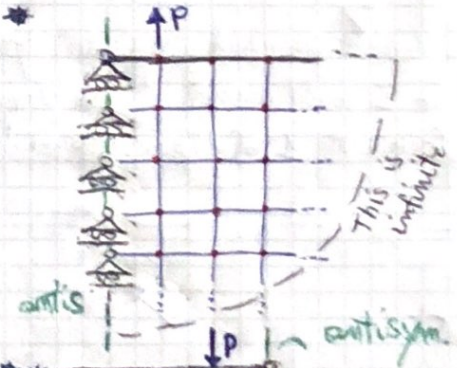
It can be divided into a quarters:



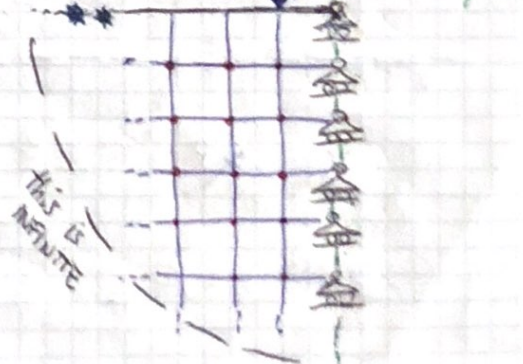
It can be divided into two halves:

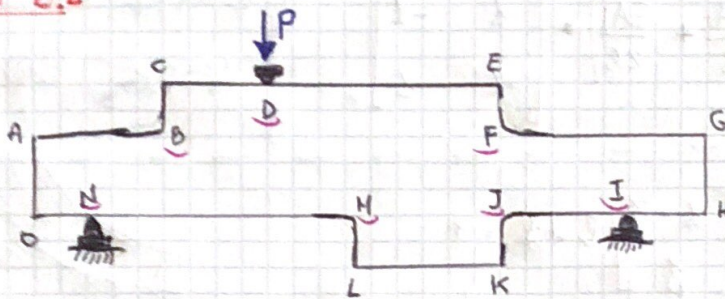


It can be divided into two halves



or:





B-F-J-M] → all are entrant corners, regions where the isotropic stresses gather.

N-I] → vicinity of sharp (pointy) contact areas.

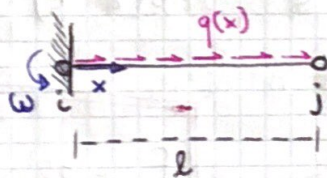
D] → vicinity of concentrated load.

Assignment 2.3

for simplicity

$$A = A(\xi) = A_i(1-\xi) + A_j\xi, \quad \xi = \frac{x-x_i}{l} \quad (x_i \neq 0)$$

$$q(x) = \rho A \omega^2 x$$



I write down the shape forms: $N_1^e = 1 - \frac{x}{l}$ $N_2^e = \frac{x}{l}$ $\underline{N}^e = [N_1^e \quad N_2^e]$

So that $\underline{u}(x) = \underline{N}^e \underline{u}^e = (1 - \frac{x}{l}) u_i^e + \frac{x}{l} u_j^e$

once derived, $\underline{e}(x) = \frac{du}{dx} = -\frac{u_i^e}{l} + \frac{u_j^e}{l} = \underline{B} \underline{u}^e$, $\underline{B} = \begin{bmatrix} \frac{dN_1^e}{dx} & \frac{dN_2^e}{dx} \end{bmatrix} = \frac{1}{l} \begin{bmatrix} -1 & 1 \end{bmatrix}$

1) the local stiffness matrix.

$$\underline{K}^e = \int_0^l EA \underline{B}^T \underline{B} dx = \frac{E}{l^2} \int_0^l [A_i(1-\frac{x}{l}) + A_j\frac{x}{l}] \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} dx$$

$$= \frac{E}{l^2} [A_i \cdot l - A_i \frac{l^2}{2l} + A_j \frac{l^2}{2l}] \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} dx =$$

EXTRACTION

$$\underline{K}^e = \left(\frac{EA_i}{2l} + \frac{EA_j}{2l} \right) \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

EXTRA WORK

$$2) \underline{f}_{ext} = \int_0^l q(\xi) \begin{bmatrix} 1-\xi \\ \xi \end{bmatrix} l d\xi = *$$

(x_i = 0)

$$q(x) = \rho A \omega^2 x \quad \text{if } \xi = \frac{x-x_i}{l} \quad \vee \quad q(\xi) = \rho l A(\xi) \omega^2 \xi$$

$$= \rho l \omega^2 \cdot [A_i(1-\xi) + A_j \xi] \xi$$

$$* = \int_0^1 \rho l^2 \omega^2 \left[\begin{matrix} A_i(\xi - 2\xi^2 + \xi^3) + A_j(\xi^2 - \xi^3) \\ A_i(\xi^2 - \xi^3) + A_j(\xi^3) \end{matrix} \right]$$

$$= \rho l^2 \omega^2 \left[\begin{matrix} A_i \left[\frac{1}{2} - \frac{2}{3} + \frac{1}{4} \right] + A_j \left[\frac{1}{3} - \frac{1}{4} \right] \\ A_i \left[\frac{1}{3} - \frac{1}{4} \right] + A_j \frac{1}{4} \end{matrix} \right]$$

$$\underline{f}_{ext} = \rho l^2 \omega^2 \begin{bmatrix} \frac{A_i}{12} + \frac{A_j}{12} \\ \frac{A_i}{12} + \frac{A_j}{4} \end{bmatrix}$$

if A = A_i = A_j

$$\underline{f}_{ext} = \rho l^2 \omega^2 A \begin{bmatrix} \frac{1}{6} \\ \frac{1}{3} \end{bmatrix}$$

[answer to question 2.3]

So the problem is:

$$\underline{K}^e \underline{u}^e = \underline{f}^e$$

$$\left(\frac{EA_i}{2l} + \frac{EA_j}{2l} \right) \cdot \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} u_i^e \\ u_j^e \end{Bmatrix} = \rho l^2 \omega^2 \begin{bmatrix} \frac{A_i}{12} + \frac{A_j}{12} \\ \frac{A_i}{12} + \frac{A_j}{4} \end{bmatrix}$$

I consider the BC, so $\hat{K}^e u_j^e = \hat{f}^e$

$$\left(\frac{EA_i}{2l} + \frac{EA_j}{2l} \right) u_j^e = \rho l^2 \omega^2 \left[\frac{A_i}{12} + \frac{A_j}{4} \right]$$

and I solve the equation

EXTRA WORK