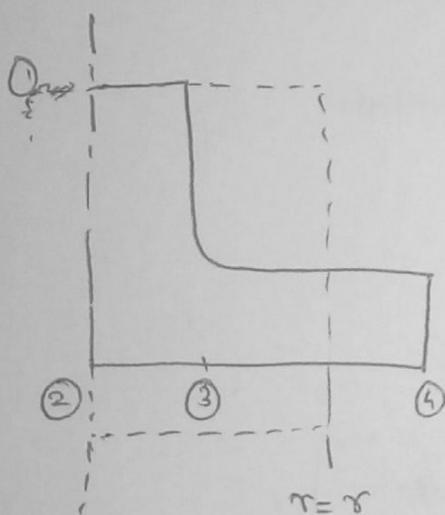


Taking the following control volume -



Applying Mass conservation in Reynolds Transport theorem form,

$$\frac{DM_{sys}}{Dt} = 0 = \frac{\partial}{\partial t} \int_{CV} \rho dV - \int_{CS} \rho \vec{v} \cdot \vec{n} ds$$

Assuming steady state,

$$0 = \int_{CS} \rho \vec{v} \cdot \vec{n} ds$$

Assuming constant density and using $V_r = f(r)$

$$0 = -\rho V \pi a^2 + 2 \rho \pi r^2 h V_r$$

$$\Rightarrow V_r = \frac{a^2 V}{2h r}$$

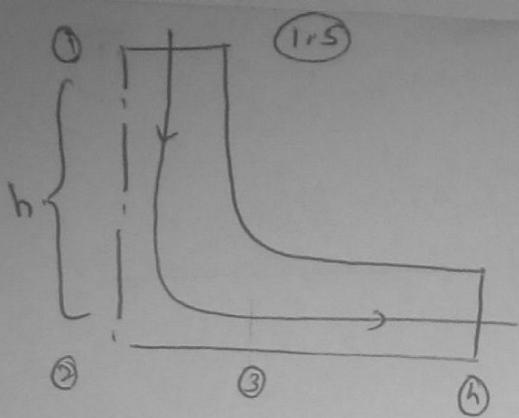
so for $r \geq a$ $V_r = \frac{c_2}{r}$ where $c_2 = \frac{a^2 V}{2h}$

The velocity field should be continuous at $r=a$ since there is no mass getting added or removed at that location.

$$\Rightarrow V_r \text{ for } r \leq a \Big|_{r=a} = V_r \text{ for } r \geq a \Big|_{r=a}$$

$$c_1 a = \frac{a^2 V}{2ha}$$

$$\Rightarrow c_1 = \frac{V}{2h}$$



Applying Bernoulli Theorem between 1 & 2
 since the flow is inviscid and assumed to incompressible and with constant ρ .

$$\int_1^2 \frac{dV}{dt} \cdot d\bar{x} + P_2 + \frac{1}{2} \rho v_2^2 - P_1 - \frac{1}{2} \rho v_1^2 - \rho g h = 0$$

\downarrow 0 (Steady state) \downarrow $v_2 = 0$ Stagnation point \downarrow very small ρ is less neglecting term

$$P_2 = P_1 + \frac{1}{2} \rho v^2$$

$P_1 =$ is given to be P_0

Applying Bernoulli Theorem between 2 & 3 (same assumptions as above)

$$P_2 + \frac{1}{2} \rho v_2^2 + 0 = P_r + \frac{1}{2} \rho v_r^2 + \rho g h^*$$

\downarrow Stagnation \downarrow small height

$$P_1 + \frac{1}{2} \rho v^2 = P_r + \frac{1}{2} \rho \left(\frac{vr}{2h} \right)^2$$

$$P_r - P_1 = \frac{1}{2} \rho v^2 \left(1 - \frac{r^2}{4h^2} \right)$$

$$P_{r, \text{gauge}} = \frac{1}{2} \rho v^2 \left(1 - \frac{r^2}{4h^2} \right) \quad r \leq a$$

Applying Bernoulli Theorem between 2 & 4 (same assumptions as above)

$$P_2 = P_r + \frac{1}{2} \rho v_r^2$$

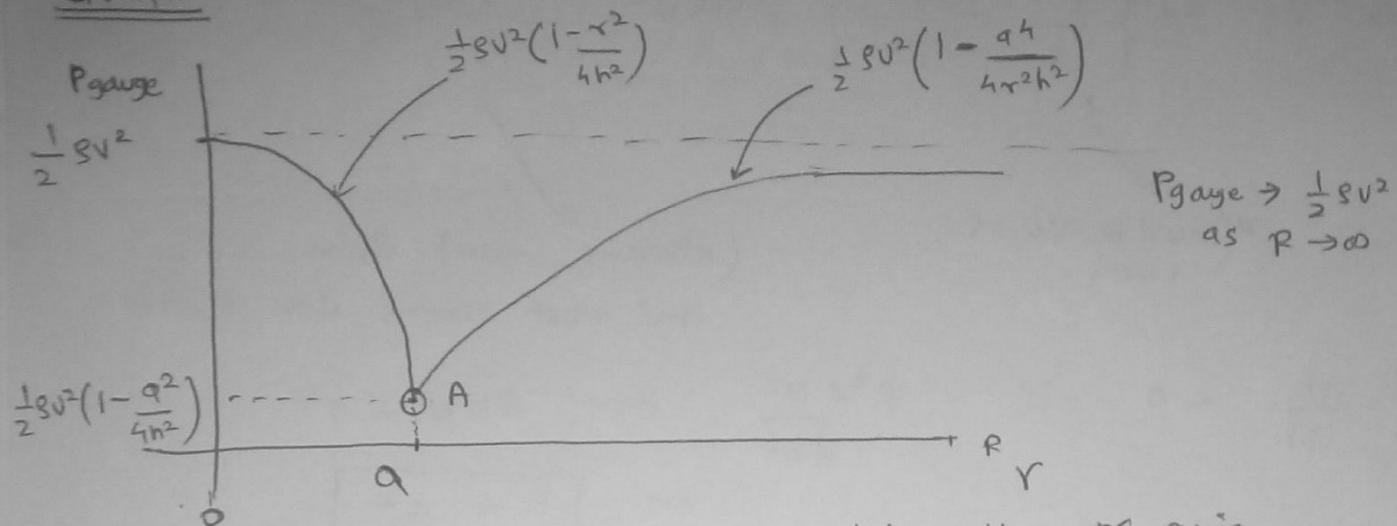
$$P_1 + \frac{1}{2} \rho v^2 = P_r + \frac{1}{2} \rho \left(\frac{a^2 v}{2rh} \right)^2$$

$$P_r - P_1 = \frac{1}{2} \rho v^2 \left(1 - \frac{a^4}{4h^2 r^2} \right)$$

$$P_{r, \text{gauge}} = \frac{1}{2} \rho v^2 \left(1 - \frac{a^4}{4r^2 h^2} \right) \quad r \geq a$$

Graph

(2)



The point A could be above or below the x axis depending on the value of $\frac{1-a^2}{4h^2}$

if $\frac{1-a^2}{4h^2} < 0$, it goes below x axis, But the overall nature and behavior, shape remains same.

Calculating the force on cardboard disk.
Total downward force acting on disk

$$\begin{aligned}
 &= \int_0^R P_r 2\pi r dr \\
 &= \int_0^a \frac{1}{2} S V^2 \left(1 - \frac{r^2}{4h^2}\right) 2\pi r dr + \int_a^R \frac{1}{2} S V^2 \left(1 - \frac{a^4}{4r^2 h^2}\right) 2\pi r dr \\
 &= \frac{2\pi S V^2}{2} \left[\frac{a^2}{2} - \frac{a^4}{16h^2} \right] + \frac{1}{2} S V^2 (2\pi) \left[\left(\frac{R^2}{2} - \frac{a^2}{2}\right) - \frac{a^4}{4h^2} \ln\left(\frac{R}{a}\right) \right]
 \end{aligned}$$

Two terms cancelled out.

$$F_{\text{total}} \downarrow = 2\pi S V^2 \left[\frac{R^2}{2} - \frac{a^4}{16h^2} \right] + \pi S V^2 \left(\frac{a^4}{4h^2} \right) \ln\left(\frac{a}{R}\right)$$

$$F_{\text{down}} = \pi \rho v^2 \left[\frac{R^2}{2} - \frac{a^4}{16h^2} \right] + \pi \rho v^2 \left(\frac{a^4}{4h^2} \right) \ln \left(\frac{a}{R} \right)$$

a (could be -ve or +ve)

(always -ve) since $a < R$ and rest terms are positive

$$\frac{R^2}{2} - \frac{a^4}{16h^2} < 0 \quad \text{if} \quad R^2 < \frac{a^4}{8h^2} \quad \text{or} \quad 8h^2 R^2 < a^4$$

$$\text{or} \quad \boxed{h < \frac{a^2}{2\sqrt{2}R}}$$

so ~~if~~

F_{down} could be less than zero.

$F_{\text{down}} =$ \pm positive or negative term + negative term.

In the given problem

$$a = 1 \text{E-}2 \text{ m}$$

$$R = 5 \text{E-}2 \text{ m}$$

$$h = 0.1 \text{E-}2 \text{ m}$$

$$M = 10 \text{E-}3 \text{ kg}$$

$$F_{\text{down}} + \text{weight disk} = 0$$

$$F_{\text{up}} = \text{weight disk}$$

$$10 \text{E-}3 \times 9.81 + \frac{\pi}{2} \rho v^2 \left[(5 \text{E-}2)^2 - \frac{(1 \text{E-}2)^4}{8(0.1 \text{E-}2)^2} + \frac{(1 \text{E-}2)^4}{2(0.1 \text{E-}2)^2} \ln \left(\frac{1 \text{E-}2}{5 \text{E-}2} \right) \right] = 0$$

$$\rho_{\text{air}} = 1.225 \text{ kg/m}^3$$

$$10 \text{E-}3 \times 9.81 = \frac{\pi}{2} (1.225 v^2) \times 6.7972 \text{E-}3$$

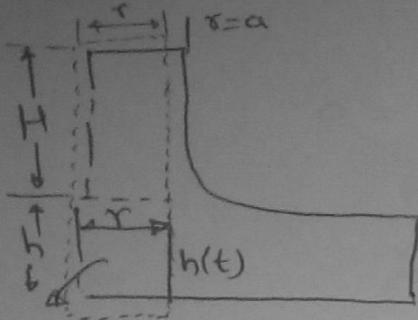
$$10 \text{E-}3 \times 9.81 = 0.013079 v^2$$

$$v^2 = 7.5$$

$$\boxed{v = 2.7386 \text{ m/s}}$$

$h = h(t)$ No longer a steady state problem.

(3)



control volume -

for $r \leq a$, Mass continuity in Reynolds Transport Theorem

$$\frac{Dm_{sys}}{Dt} = \frac{\partial}{\partial t} \int_{CV} \rho dV + \int_{CS} \rho \vec{v} \cdot \vec{n} ds$$

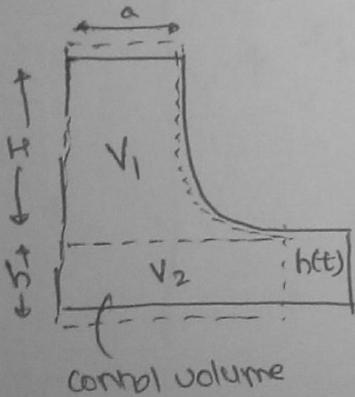
$$0 = \frac{\partial}{\partial t} (\rho \pi r^2 (h \frac{dh}{dt})) + \rho V_r 2\pi r h - \rho V \pi r^2$$

assuming $\rho = \text{constant}$ and H does not change.

$$0 = \pi r^2 \frac{dh}{dt} + V_r h 2\pi r - V \pi r^2$$

$$V_r = \frac{V_r}{2h} - \frac{r}{2h} \frac{dh}{dt} \quad r \leq a$$

for $r \gg a$ Mass continuity in Reynolds Transport Theorem and $\rho = \text{constant}$.



$$\frac{Dm_{sys}}{Dt} = \frac{\partial}{\partial t} \int_{CV} \rho dV + \int_{CS} \rho \vec{v} \cdot \vec{n} ds$$

$$0 = \frac{\partial}{\partial t} (\pi V_1 + V_2) + 2\pi r h V_r - V \pi a^2$$

$$\frac{\partial V_1}{\partial t} = 0 \quad \frac{\partial V_2}{\partial t} = \pi r^2 \frac{dh}{dt}$$

$$\frac{\pi r^2}{2h} \frac{dh}{dt} = \frac{V_r^2}{2rh} \pi a^2 - 2\pi r h V_r$$

$$V_r = \frac{V a^2}{2rh} - \frac{r}{2h} \frac{dh}{dt} \quad r \gg a$$

3.5 Using these expressions and applying Bernoulli between $r=0$ to $r=R$ (2 to 4)

$$\int_0^R \frac{\partial \bar{v}}{\partial t} \cdot d\bar{r} + P_R + \frac{1}{2} \rho V_R^2 = P_2 - \frac{1}{2} \rho V_2^2 = 0$$

given $P_R = P_0$ or P_1

and $P_2 = P_1 + \frac{1}{2} \rho V^2$ and $P_1 = P_0$

$$= P_0 + \frac{1}{2} \rho V^2$$

$$P_R - P_2 = -\frac{1}{2} \rho V^2$$

$$V_P = \frac{Va^2}{2Rh} - \frac{R}{2h} \left(\frac{dh}{dt} \right)$$

$$\int_0^a \frac{\partial \bar{v}}{\partial t} \cdot d\bar{r} + \int_a^R \frac{\partial \bar{v}}{\partial t} \cdot d\bar{r} = \frac{1}{2} \rho V^2 + \frac{1}{2} \rho \left[\frac{Va^2}{2Rh} - \frac{R}{2h} \frac{dh}{dt} \right]^2 = 0$$

~~1/2~~

$$\int_0^a \rho \left[-\frac{Vr}{2h^2} \frac{dh}{dt} + \frac{r}{2h^2} \left(\frac{dh}{dt} \right)^2 - \frac{r}{2h} \frac{d^2h}{dt^2} \right] dr +$$

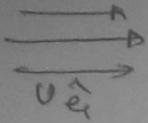
$$\int_a^R \rho \left[-\frac{Va^2}{2rh^2} \frac{dh}{dt} + \frac{r}{2h^2} \left(\frac{dh}{dt} \right)^2 - \frac{r}{2h} \frac{d^2h}{dt^2} \right] dr - \frac{1}{2} \rho V^2 +$$

a

$$\frac{1}{2} \rho \left[\frac{Va^2}{2Rh} - \frac{R}{2h} \frac{dh}{dt} \right]^2 = 0$$

Q.2

(h)



(a) let's work in cylindrical polar coordinates. $\vec{v} = v(r, \theta)$ (2D flow)

BC 1

Irrespective of θ , when $r \rightarrow \infty$, $v(r, \theta)$ should become $U \hat{e}_1$

$$\vec{v}(r, \theta) \Big|_{r \rightarrow \infty} = U \hat{e}_1$$

BC 2

velocity along the surface of cylinder should not be radial. Fluid should move parallel to the boundary, i.e. there cannot be a flux of fluid at this boundary.

$$\vec{v}(r, \theta) \Big|_{r=R} = v_\theta \hat{e}_\theta$$

(b) The flow velocity is $U \hat{e}_1$ so $\nabla \times \vec{v} = 0$. Flow is irrotational initially. Since the flow is inviscid the irrotationality should be conserved. In that case, the stream function should satisfy the Laplace equation.

$$\nabla^2 \psi = 0 \quad \text{where} \quad \psi = r^\alpha \sin \theta$$

In polar form, (2D)

$$\nabla^2 \psi = \frac{\partial^2 \psi}{\partial r^2} + \frac{1}{r} \frac{\partial \psi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \theta^2}$$

$$0 = \frac{\partial}{\partial r} \left(\alpha(\alpha-1) r^{\alpha-2} \sin \theta \right) + \frac{1}{r} \times \alpha \times r^{\alpha-1} \sin \theta$$

$$+ \frac{1}{r^2} (-r^\alpha) \sin \theta$$

Cancel $r^{\alpha-2}$ from all sides and $\sin \theta$

$$0 = \alpha(\alpha-1) + \alpha - 1$$

$$0 = \alpha^2 - 1$$

$$\boxed{\alpha = \pm 1}$$

(4.5) Since $\nabla^2 \psi = 0$ is a second order diff. Equation. and is linear $\psi_1 + \psi_2 = \psi_3$ is also a solution. so a general solution can be written as,

$$\psi = \frac{a_1 \sin \theta}{r} + a_2 r \sin \theta$$

(C) \Rightarrow

Now a_1, a_2 can be found using BC.

$$V_r = \frac{1}{r} \left(\frac{a_1 \cos \theta}{r} + a_2 r \cos \theta \right)$$

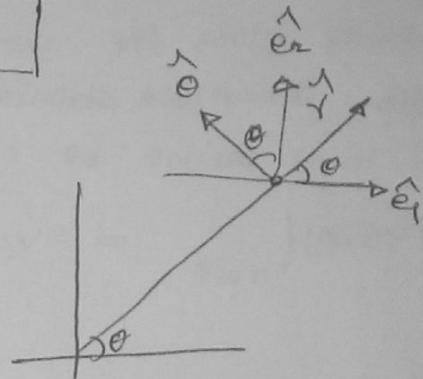
$$V_\theta = \frac{a_1 \sin \theta}{r^2} - a_2 \sin \theta$$

lets check for BC 1

as $r \rightarrow \infty$

$$V_r \rightarrow a_2 \cos \theta \hat{r}$$

$$V_\theta \rightarrow -a_2 \sin \theta \hat{\theta}$$



$$\hat{e}_1 = \hat{r} \cos \theta - \hat{\theta} \sin \theta$$

$$\hat{e}_2 = \hat{r} \sin \theta + \hat{\theta} \cos \theta$$

$$\text{so } V_x = (V_r \cos \theta - V_\theta \sin \theta) \hat{e}_1$$

$$= a_2 \cos^2 \theta + a_2 \sin^2 \theta = (a_2) \hat{e}_1$$

$$\text{also } V_y = (V_r \sin \theta + V_\theta \cos \theta) \hat{e}_2$$

$$= a_2 \cos \theta \sin \theta - a_2 \sin \theta \cos \theta = 0 \hat{e}_2$$

so as $r \rightarrow \infty$
 \vec{V} is $a_2 \hat{e}_1$

using BC we know as $r \rightarrow \infty$ \vec{V} should be $U \hat{e}_1$

$$\Rightarrow \boxed{a_2 = U}$$

Now using BC 2

(5)

$$\bar{v}(r, \theta) \Big|_{r=R} = \left(\frac{a_1 \cos \theta}{R^2} + a_2 \cos \theta \right) \hat{r} + \left(\frac{a_1 \sin \theta}{R^2} - a_2 \sin \theta \right) \hat{\theta}$$

We get that $v_r = 0$ from BC 2 condition.

$$\frac{a_1 \cos \theta}{R^2} + a_2 \cos \theta = 0$$

$$a_2 = -a_1$$

$$\frac{a_1 \cos \theta}{R^2} + a_1 \cos \theta = 0$$

$$a_1 \left(\frac{1}{R^2} + 1 \right) \cos \theta = 0$$

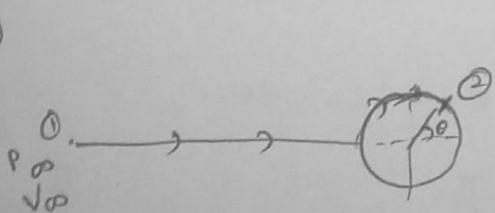
$$a_1 = -UR^2$$

so

$$v_r = U \left(1 - \frac{R^2}{r^2} \right) \cos \theta$$

$$v_\theta = -U \left(1 + \frac{R^2}{r^2} \right) \sin \theta$$

(d)



Applying Bernoulli theorem from ① to ②

$$P_0 + \frac{1}{2} \rho v_0^2 = P_2 + \frac{1}{2} \rho v_2^2$$

$$P_2 = P_0 + \frac{1}{2} \rho v_0^2 - \frac{1}{2} \rho v_2^2$$

$\|v_2\| = \|v\| \Big|_{r=R, \theta=\theta} = v_r$ at $r=R \Rightarrow 0$ only v_θ component.

$$v_\theta \Big|_{r=R} = -2U \sin \theta$$

(5.5)

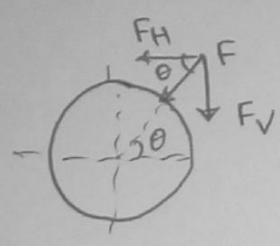
$$P_2 = P_\infty + \frac{1}{2} \rho U^2 - \frac{1}{2} \rho (2U \sin \theta)^2$$

$$= P_\infty + \frac{1}{2} \rho (U^2 - 2U^2 \sin^2 \theta)$$

$$= P_\infty + \frac{1}{2} \rho U^2 (1 - \sin^2 \theta)$$

$$P_2 = P_\infty + \rho U^2 \left(\cos^2 \theta - \frac{1}{2} \right)$$

(B) Net force on cylinder.



$$F_H = - \int_0^{2\pi} P R d\theta \cos \theta$$

$$F_V = - \int_0^{2\pi} P R d\theta \sin \theta$$

$$F_H = - \int_0^{2\pi} \rho U^2 \left(\cos^2 \theta - \frac{1}{2} \right) R d\theta \cos \theta = (-\rho U^2 R) \left[\int_0^{2\pi} \cos^3 \theta d\theta - \frac{1}{2} \int_0^{2\pi} \cos \theta d\theta \right]$$

$$P = \int_0^{2\pi} \cos^2 \theta \cos \theta d\theta = \cos \theta \int_0^{2\pi} \cos^2 \theta d\theta - \int_0^{2\pi} \frac{\sin \theta \sin^2 \theta}{2} d\theta$$

$$= \cos \theta \int_0^{2\pi} \cos^2 \theta d\theta - \left[\sin \theta \int \sin^2 \theta - \frac{P}{2} \right]$$

$$\frac{P}{2} = \left[\frac{-\cos \theta \sin^2 \theta}{2} \right]_0^{2\pi} - \left[\frac{\sin \theta \cos^2 \theta}{2} \right]_0^{2\pi}$$

$$F_H = -\rho U^2 R \left[0 - \frac{1}{2} \int_0^{2\pi} \cos \theta d\theta \right] = 0 \quad \boxed{F_H = 0}$$

$$F_V = - \int_0^{2\pi} P R d\theta \sin \theta = - \int_{-\pi}^{\pi} \rho U^2 R \left(\cos^2 \theta - \frac{1}{2} \right) \sin \theta d\theta$$

$$= - \int_{-\pi}^{\pi} \rho U^2 R \cos^2 \theta \sin \theta d\theta + \int_{-\pi}^{\pi} \frac{\rho U^2 R}{2} \sin \theta d\theta$$

(odd function) (odd function)

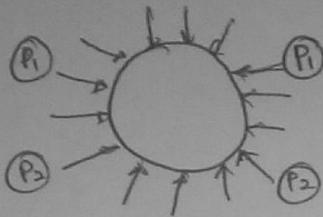
$$\boxed{F_V = 0}$$

Net force is zero. In reality it should have been nonzero value ($F_H \neq 0$) ($F_V = 0$ by symmetry) (6)

But in our problem we are not taking viscosity.

So the fluid cannot apply any force on the cylinder (friction) ~~(shear)~~

For the force by fluid pressure, the distribution is symmetric about $(\pi - \theta)$



$$\cos(2(\pi - \theta)) = \cos(-2\theta) = \cos 2\theta$$

So no force is due to pressure as well.

Note:

Description of boundary conditions in terms of ψ .

BC 1

$$V(r, \theta) \Big|_{r \rightarrow \infty} = U \hat{e}_1 \Rightarrow V_r = U \cos \theta$$

$$V_\theta = -U \sin \theta$$

$$\Rightarrow \left. \frac{1}{r} \frac{\partial \psi}{\partial \theta} \right|_{r \rightarrow \infty} = U \cos \theta$$

$$\left. -\frac{\partial \psi}{\partial r} \right|_{r \rightarrow \infty} = -U \sin \theta$$

BC 2

$$V_\theta \Big|_{r=R} = -2U \sin \theta \quad V_r \Big|_{r=R} = 0$$

$$\Rightarrow \left. \frac{1}{r} \frac{\partial \psi}{\partial \theta} \right|_{r=R} = 0 \Rightarrow \boxed{\psi = \text{constant} \cdot f(r)}$$

independency on θ .

$$\left. -\frac{\partial \psi}{\partial r} \right|_{r=R} = -2U \sin \theta$$